

Sketched Learning from Random Features Moments

Nicolas Keriven

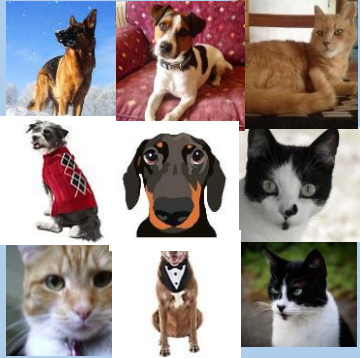
Ecole Normale Supérieure (Paris)
CFM-ENS chair in Data Science

(thesis with Rémi Gribonval at Inria Rennes)

Imaging in Paris, Apr. 5th 2018

Context: machine learning

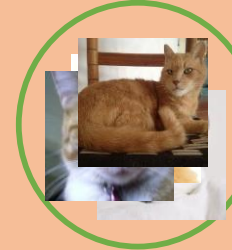
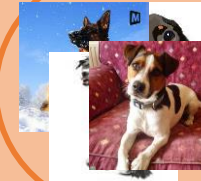
Database



Learning

Task

- Clustering



- Classification



- etc...

Context: machine learning

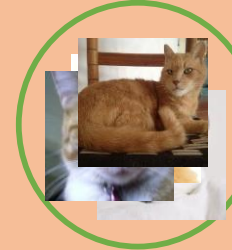
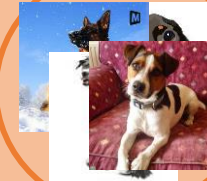
Large database



Learning

Task

- Clustering



- Classification



= cat

- etc...

Context: machine learning

Large database

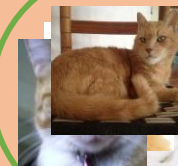
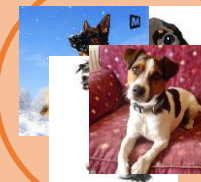


Learning

Slow, costly

Task

- Clustering



- Classification



= cat

- etc...

Context: machine learning

Large database



Learning

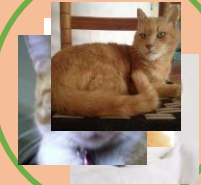
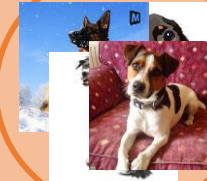
Slow, costly

Distributed database



Task

- Clustering



- Classification



= cat

- etc...

Context: machine learning

Large database



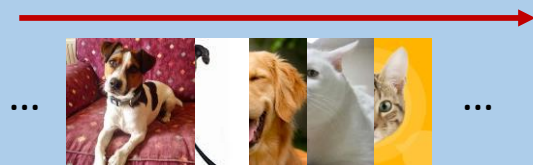
Learning

Slow, costly

Distributed database

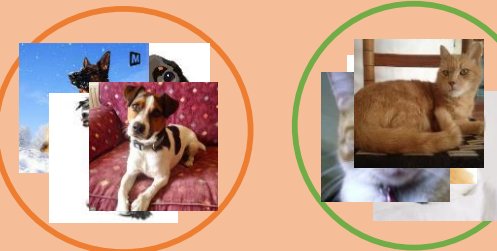


Data Stream



Task

- Clustering



- Classification



- etc...

Context: machine learning

Large database

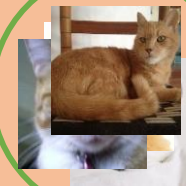
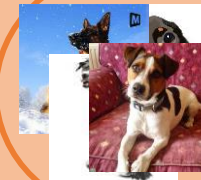


Learning

Slow, costly

Task

- Clustering



- Classification



= cat

- etc...

Distributed database



Data Stream

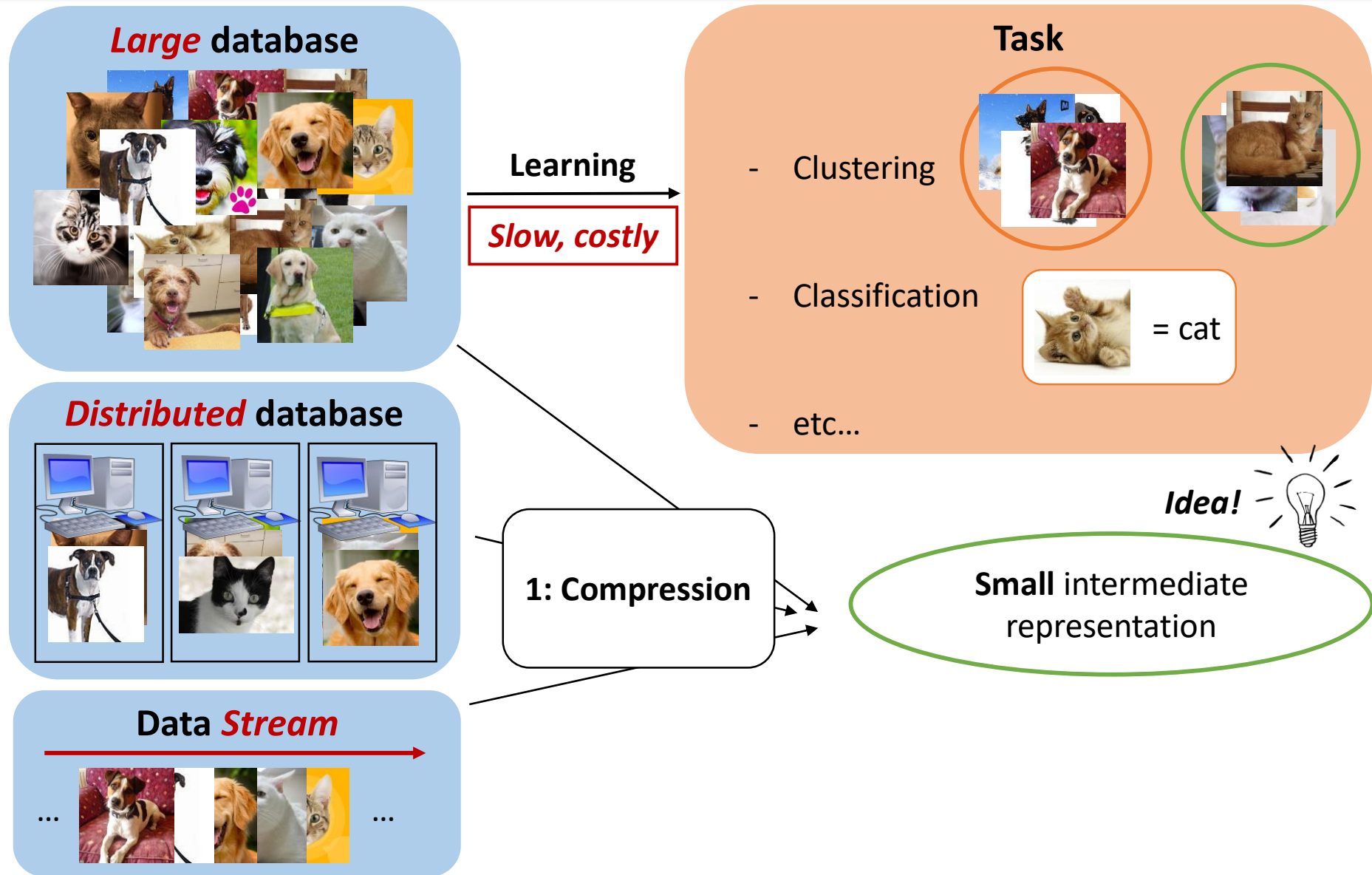


Idea!

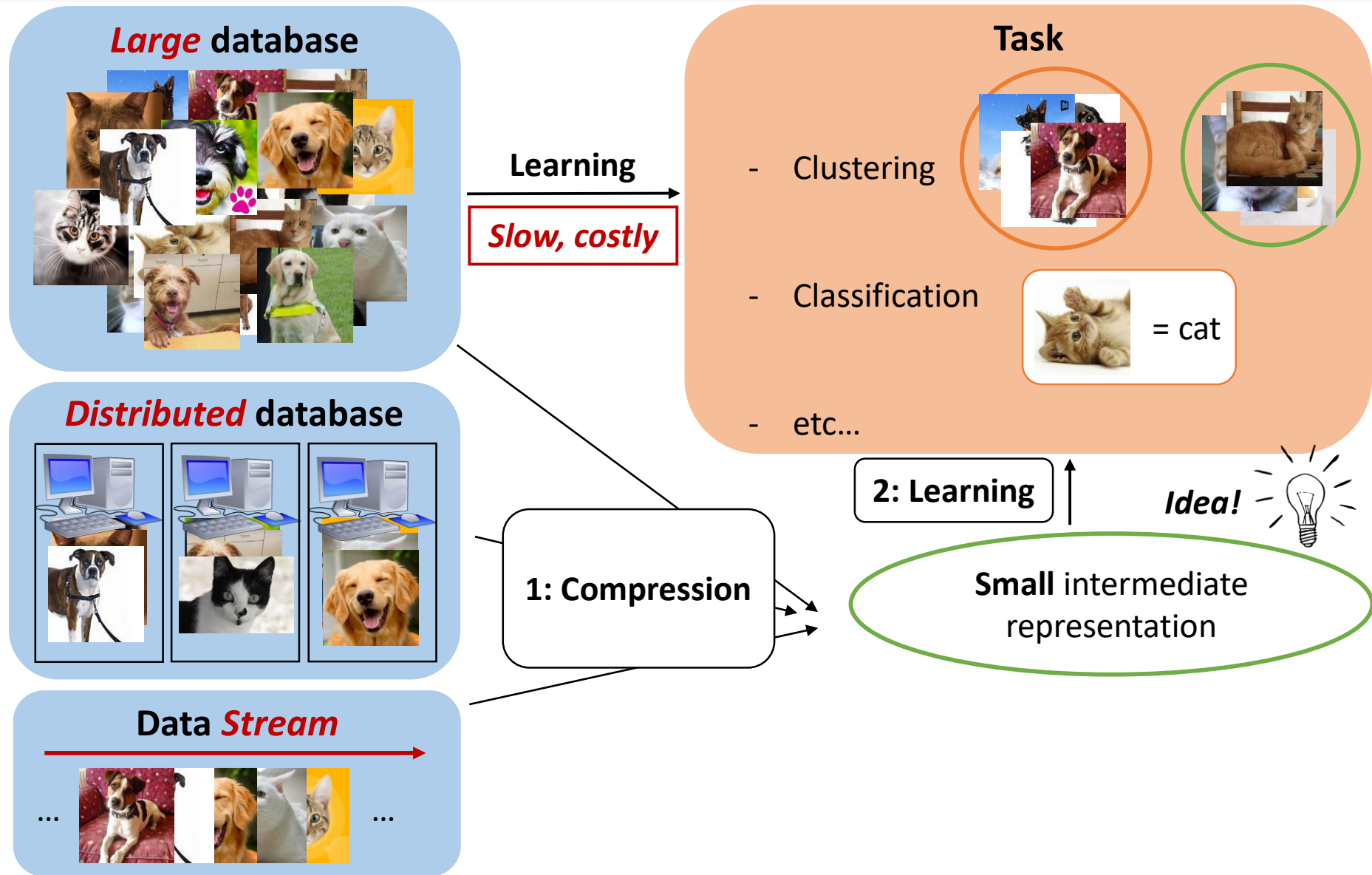


Small intermediate representation

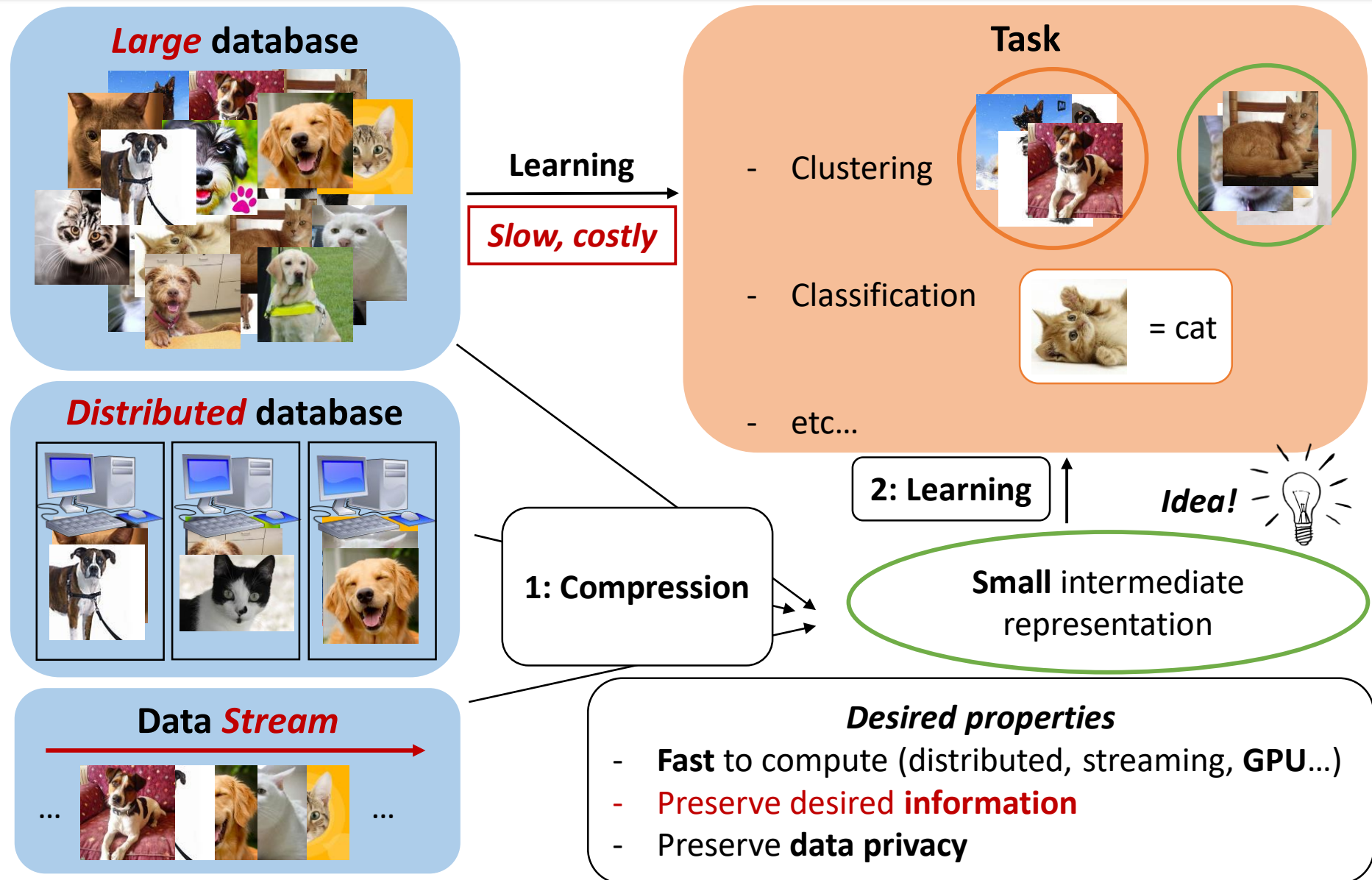
Context: machine learning



Context: machine learning



Context: machine learning



Three compression schemes

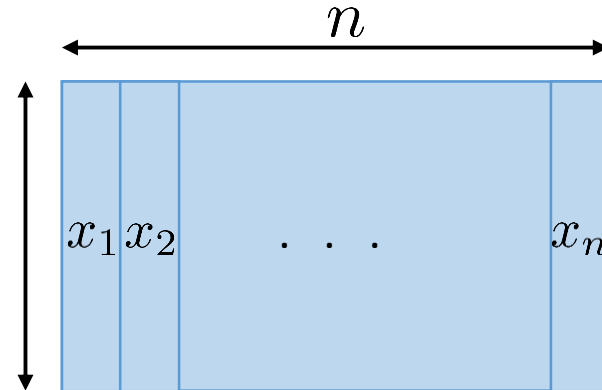
Database



Feature
extraction



d



Data = Collection of vectors

Three compression schemes

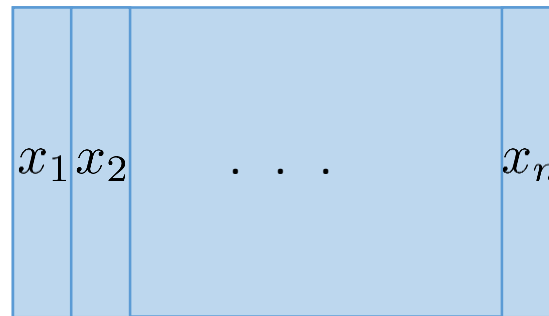
Database



Feature
extraction

d

n



Compression ?



Data = Collection of vectors

Three compression schemes

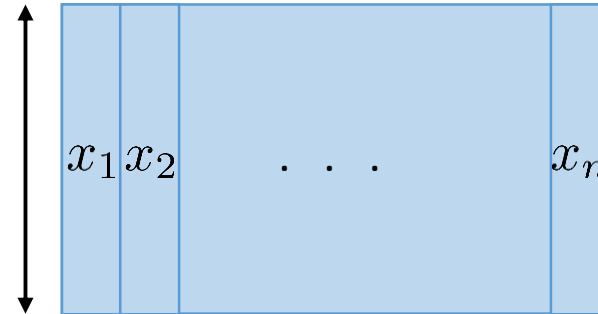
Database



Feature
extraction

d

n

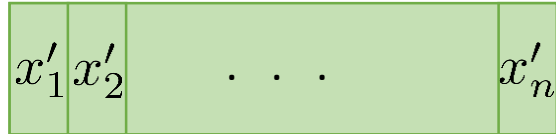


Compression ?



Data = Collection of vectors

n



Dimensionality reduction

See eg [Calderbank 2009,
Boutsidis 2010]

- Random Projection
- Feature selection

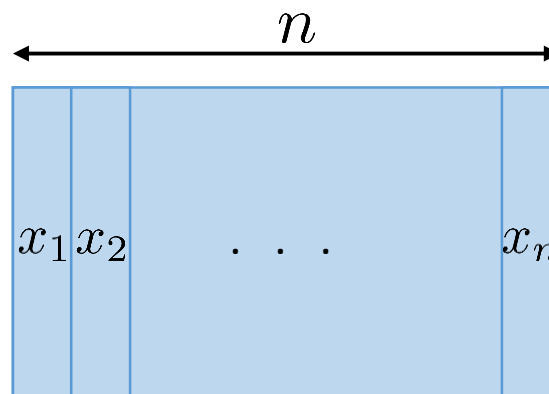
Three compression schemes

Database



Feature
extraction

d



Compression ?

Data = Collection of vectors

n



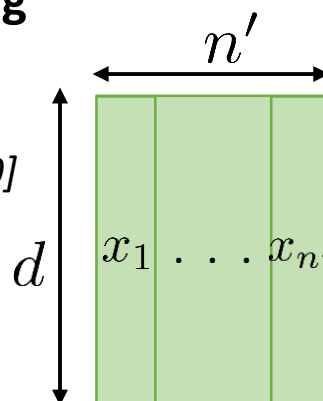
Dimensionality reduction

See eg [Calderbank 2009,
Boutsidis 2010]

- Random Projection
- Feature selection

Subsampling coresets

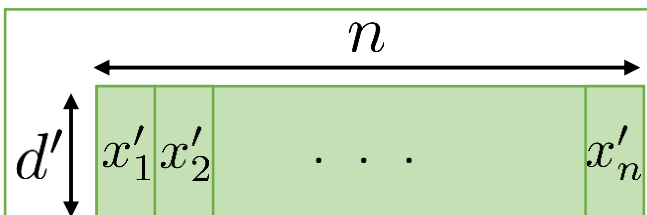
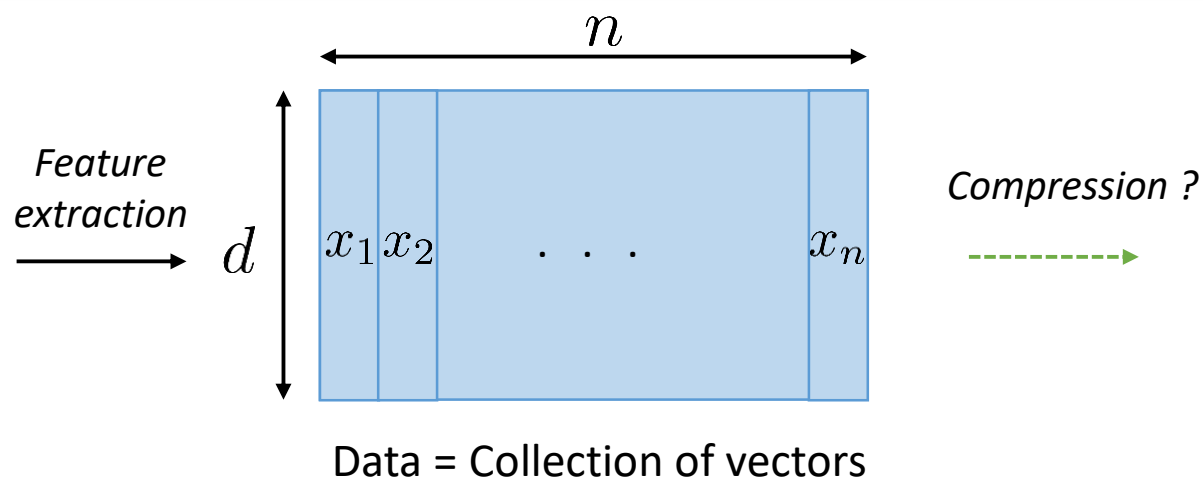
See eg
[Feldman 2010]



- Uniform sampling (naive)
- Adaptive sampling...

Three compression schemes

Database



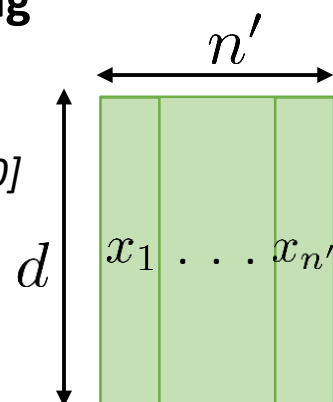
Dimensionality reduction

See eg [Calderbank 2009, Boutsidis 2010]

- Random Projection
- Feature selection

Subsampling coresets

See eg [Feldman 2010]

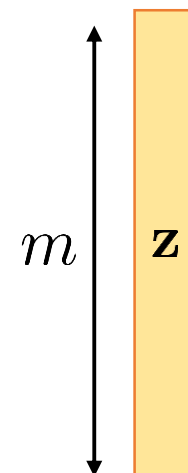


- Uniform sampling (naive)
- Adaptive sampling...

Linear sketch

See [Thaper 2002]
[Cormode 2011]

Distributed,
streaming



- Hash tables, histograms
- **Sketching for learning ?**

How-to: build a sketch

What is a sketch ?

Any *linear* sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

How-to: build a sketch

What is a sketch ?

Any *linear* sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

How-to: build a sketch

What is a sketch ?

Any *linear* sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean

How-to: build a sketch

What is a sketch ?

Any *linear* sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment

How-to: build a sketch

What is a sketch ?

Any **linear** sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [\mathbf{1}_{x \in B_i}]_{i=1}^m$: histogram

How-to: build a sketch

What is a sketch ?

Any **linear** sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [\mathbf{1}_{x \in B_i}]_{i=1}^m$: histogram
- Proposed: **kernel random features**
[Rahimi 2007]
(random proj. + non-linearity)

How-to: build a sketch

What is a sketch ?

Any *linear* sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [\mathbf{1}_{x \in B_i}]_{i=1}^m$: histogram
- Proposed: **kernel random features**
[Rahimi 2007]
(random proj. + non-linearity)

Questions:

- What information is preserved by the sketching ?
- How to retrieve this information ?
- What is a sufficient number of features ?

How-to: build a sketch

What is a sketch ?

Any *linear* sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [1_{x \in B_i}]_{i=1}^m$: histogram
- Proposed: **kernel random features**
[Rahimi 2007]
(random proj. + non-linearity)

Questions:

- What information is preserved by the sketching ?
- How to retrieve this information ?
- What is a sufficient number of features ?

Intuition: sketching as a **linear embedding**

How-to: build a sketch

What is a sketch ?

Any **linear** sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [1_{x \in B_i}]_{i=1}^m$: histogram
- Proposed: **kernel random features**
[Rahimi 2007]
(random proj. + non-linearity)

Questions:

- What information is preserved by the sketching ?
- How to retrieve this information ?
- What is a sufficient number of features ?

Intuition: sketching as a **linear embedding**

- Assumption: $x_1, \dots, x_n \stackrel{i.i.d.}{\sim} \pi^*$

How-to: build a sketch

What is a sketch ?

Any **linear** sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [1_{x \in B_i}]_{i=1}^m$: histogram
- Proposed: **kernel random features**
[Rahimi 2007]
(random proj. + non-linearity)

Questions:

- What information is preserved by the sketching ?
- How to retrieve this information ?
- What is a sufficient number of features ?

Intuition: sketching as a **linear embedding**

- Assumption: $x_1, \dots, x_n \stackrel{i.i.d.}{\sim} \pi^*$
- Linear operator: $\mathcal{A}\pi = \mathbb{E}_{X \sim \pi} \Phi(X)$

How-to: build a sketch

What is a sketch ?

Any **linear** sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [1_{x \in B_i}]_{i=1}^m$: histogram
- Proposed: **kernel random features**
[Rahimi 2007]
(random proj. + non-linearity)

Questions:

- What information is preserved by the sketching ?
- How to retrieve this information ?
- What is a sufficient number of features ?

Intuition: sketching as a **linear embedding**

- Assumption: $x_1, \dots, x_n \stackrel{i.i.d.}{\sim} \pi^*$
- Linear operator: $\mathcal{A}\pi = \mathbb{E}_{X \sim \pi} \Phi(X)$
- « Noisy » linear measurement:

$$\hat{\mathbf{z}} = \mathcal{A}\pi^* + \hat{\mathbf{e}}$$

Noise $\hat{\mathbf{e}} = \hat{\mathbb{E}}\Phi(X) - \mathbb{E}_{\pi^*}\Phi(X)$ **small**

How-to: build a sketch

What is a sketch ?

Any **linear** sketch = empirical moments

$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X) = \frac{1}{n} \sum_i \Phi(x_i)$$

What is contained in a sketch ?

- $\Phi(x) = x$: mean
- $\Phi(x) = x^k$: k^{th} moment
- $\Phi(x) = [1_{x \in B_i}]_{i=1}^m$: histogram
- Proposed: **kernel random features**
[Rahimi 2007]
(random proj. + non-linearity)

Questions:

- What information is preserved by the sketching ?
- How to retrieve this information ?
- What is a sufficient number of features ?

Intuition: sketching as a **linear embedding**

- Assumption: $x_1, \dots, x_n \stackrel{i.i.d.}{\sim} \pi^*$
- Linear operator: $\mathcal{A}\pi = \mathbb{E}_{X \sim \pi} \Phi(X)$
- « Noisy » linear measurement:

$$\hat{\mathbf{z}} = \mathcal{A}\pi^* + \hat{\mathbf{e}}$$

Noise $\hat{\mathbf{e}} = \hat{\mathbb{E}}\Phi(X) - \mathbb{E}_{\pi^*}\Phi(X)$ *small*

Dimensionality-reducing, random, linear embedding: Compressive Sensing?

Compressive Sensing: sparsity ?

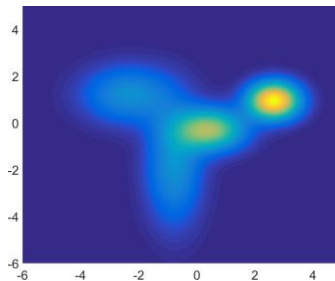
Compressive Sensing:

Classical compressive sensing



X

Sketched learning in this talk



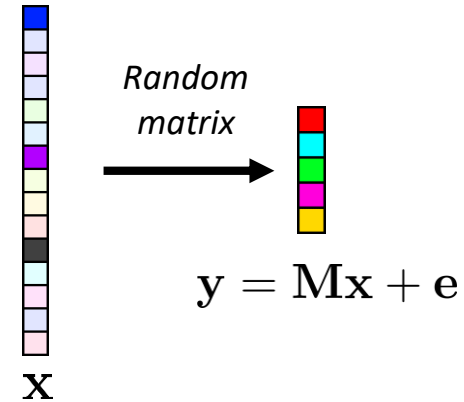
π^*

Compressive Sensing: sparsity ?

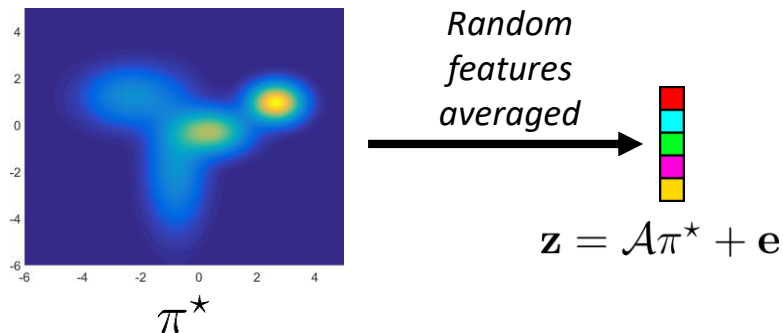
Compressive Sensing:

- Dimensionality reduction, random operator

Classical compressive sensing



Sketched learning in this talk

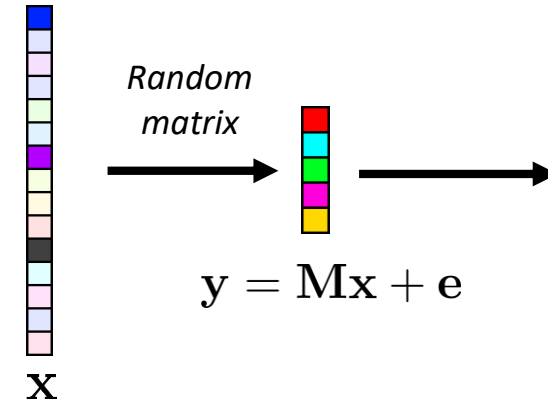


Compressive Sensing: sparsity ?

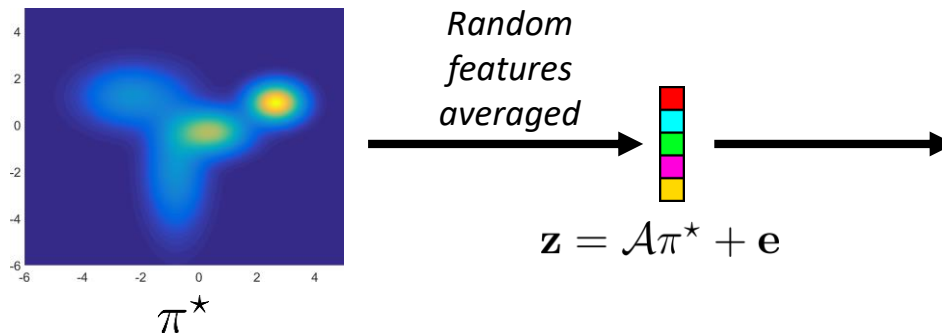
Compressive Sensing:

- Dimensionality reduction, random operator
- (Ill-posed) **inverse problem**: *density estimation*

Classical compressive sensing



Sketched learning in this talk

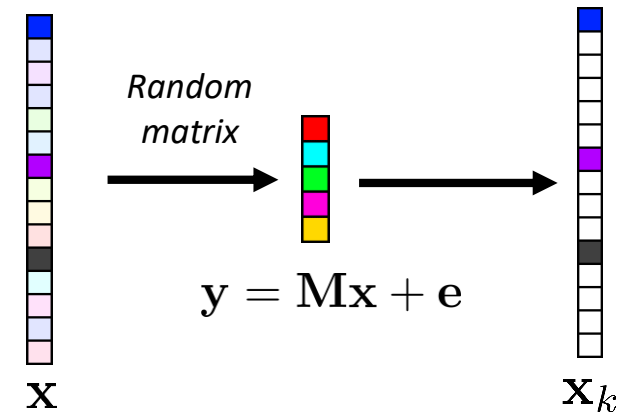


Compressive Sensing: sparsity ?

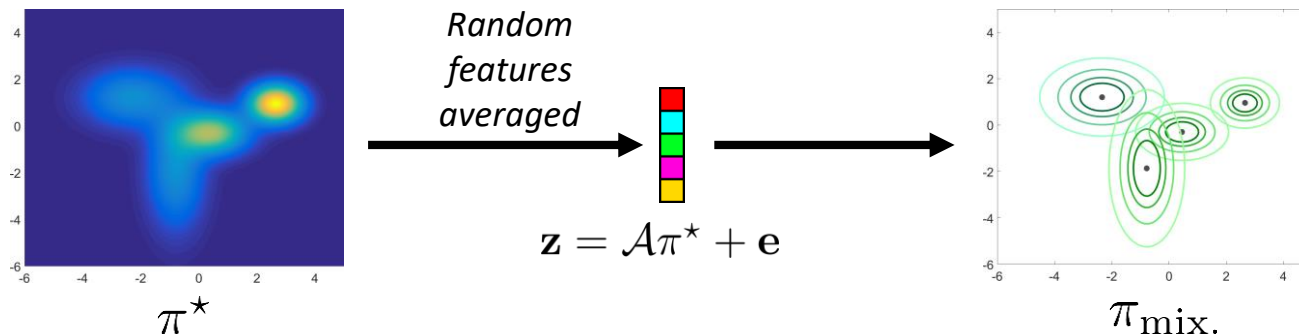
Compressive Sensing:

- Dimensionality reduction, random operator
- (Ill-posed) **inverse problem**: *density estimation*
- **Sparsity**: « simple » densities (mixture model)

Classical compressive sensing

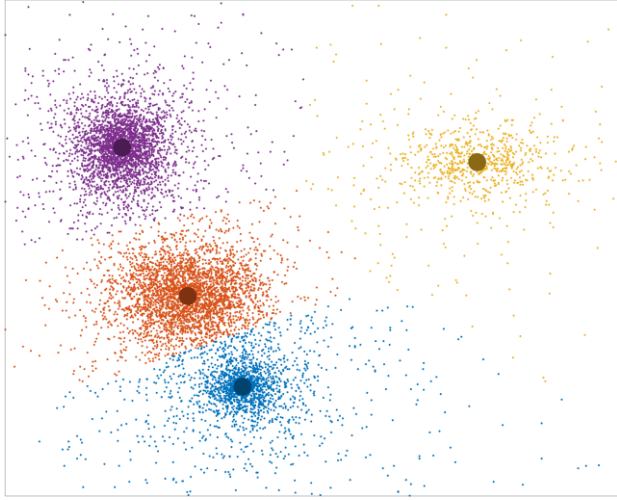


Sketched learning in this talk



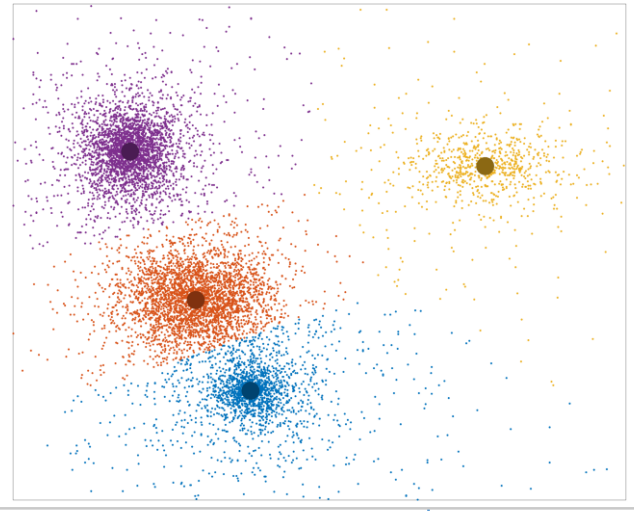
Result: Compressive k-means [Keriven et al 2017]

Mixture of Diracs = k-means



Result: Compressive k-means [Keriven et al 2017]

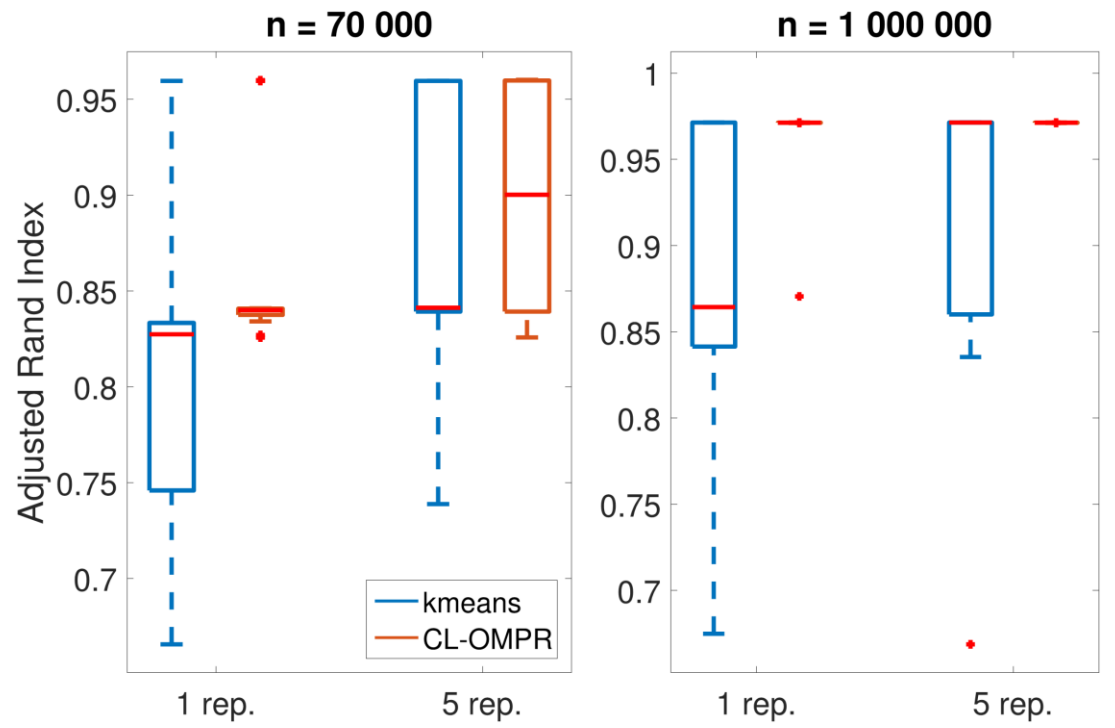
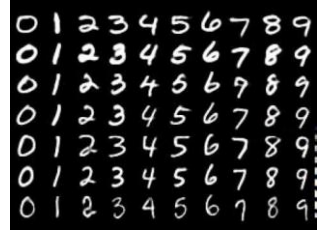
Mixture of Diracs = k-means



Classif. Perf.

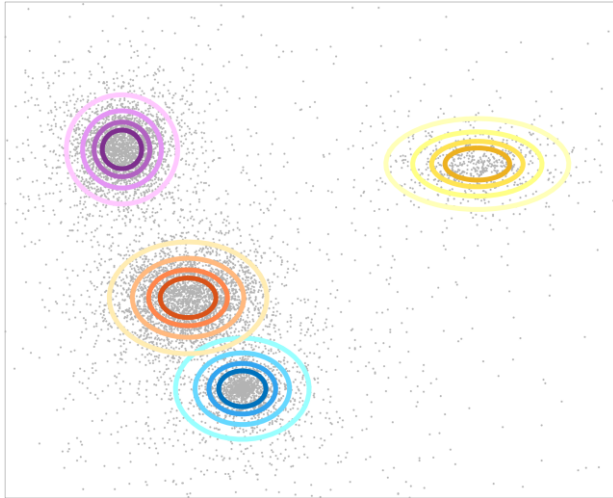
- Twice faster than k-means
- 4 orders of magnitude more memory efficient

Application: Spectral clustering for MNIST classification [Uw 2001]



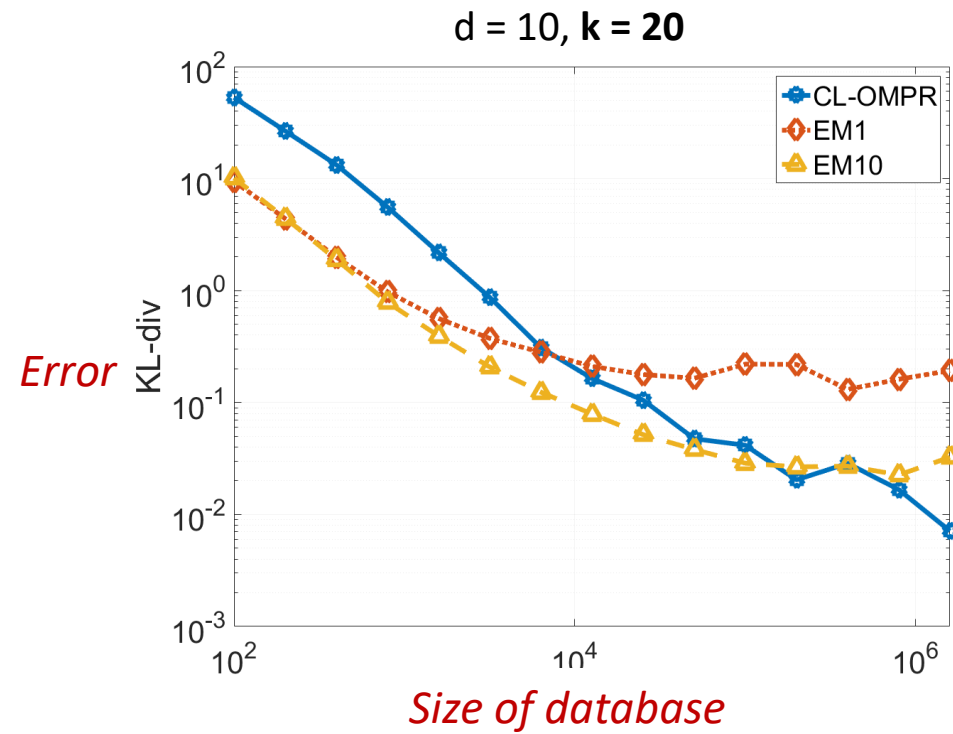
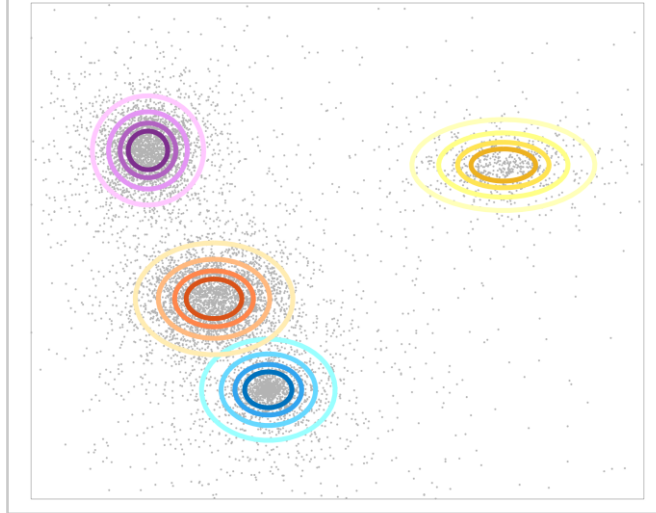
Gaussian mixture models

GMM



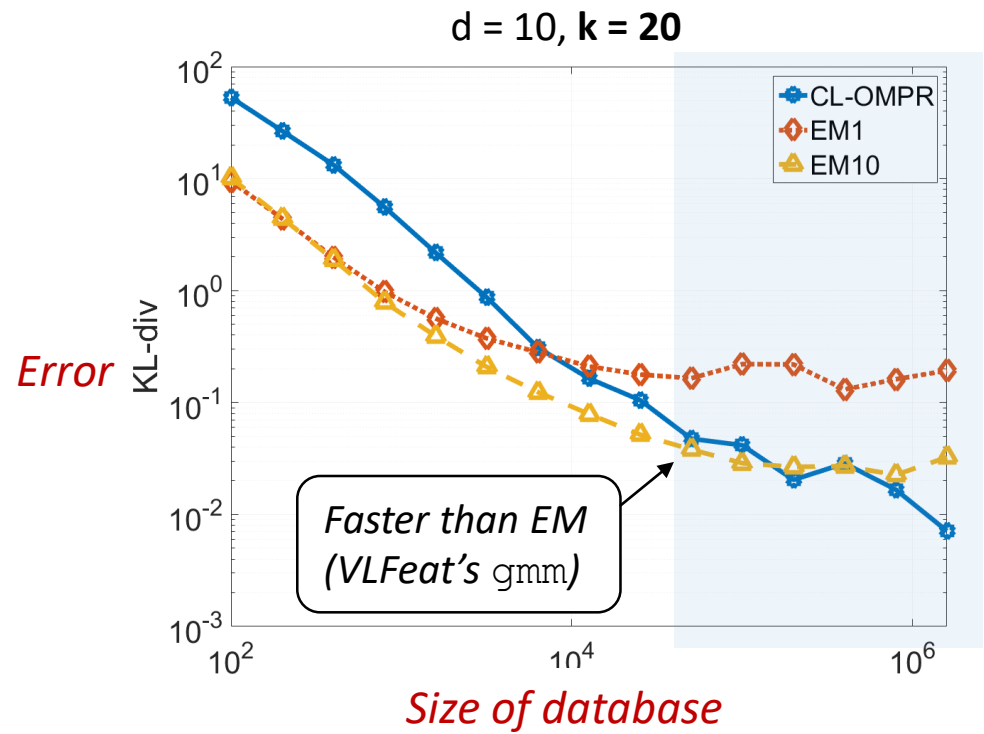
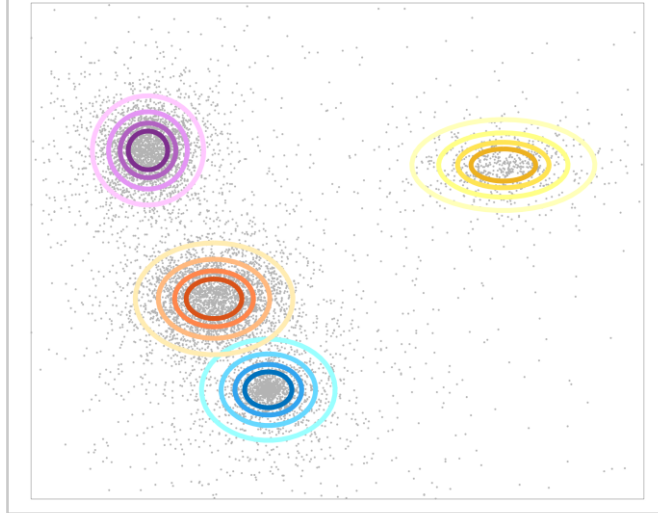
Gaussian mixture models

GMM



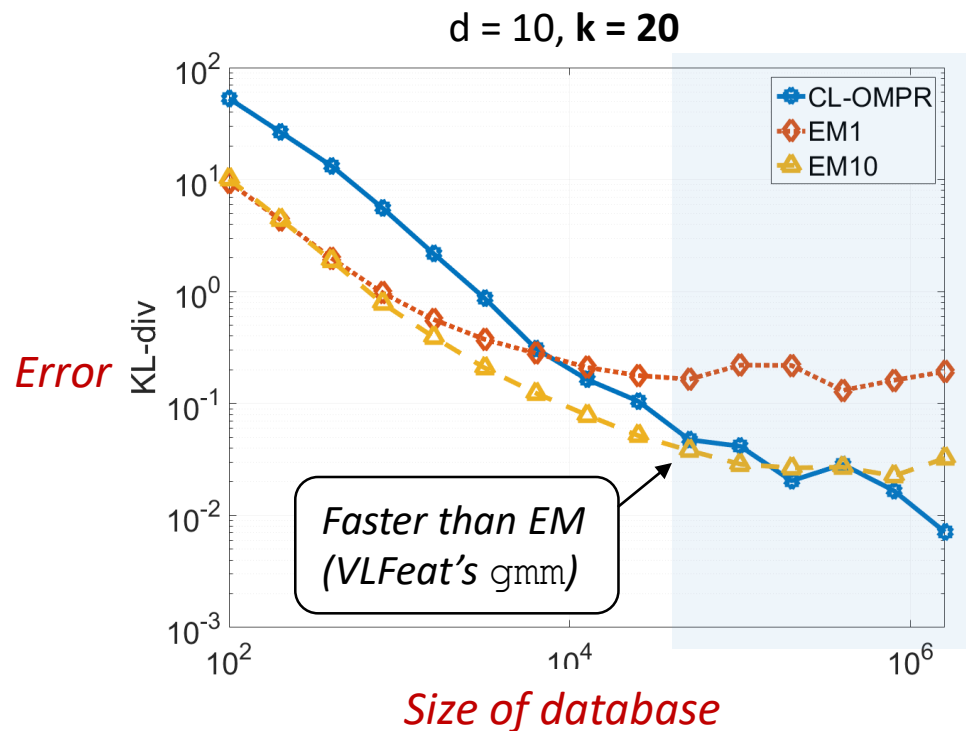
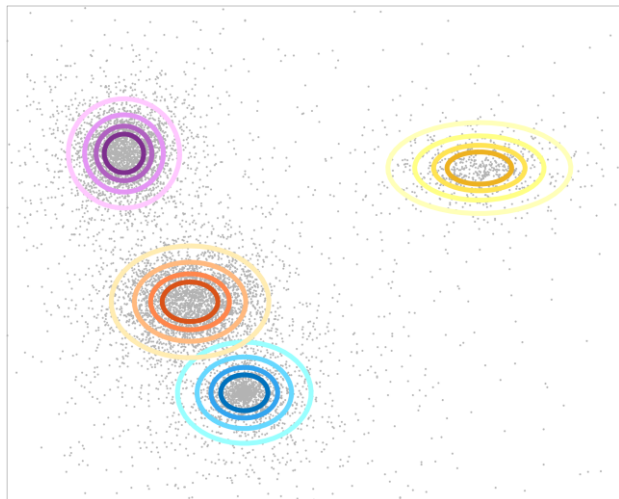
Gaussian mixture models

GMM



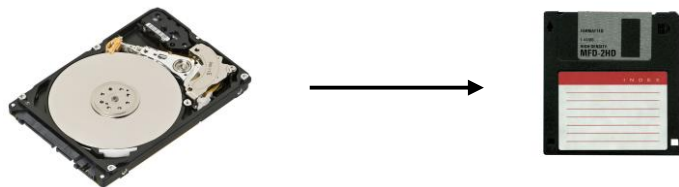
Gaussian mixture models

GMM



Application: speaker verification [Reynolds 2000] ($d=12, k=64$)

- EM on 300 000 vectors : **29.53**
- **20kB** sketch computed on **50GB** database: **28.96**



Q: Theoretical guarantees ?

- Inspired by Compressive Sensing:
 - 1: with the Restricted Isometry Property (RIP)
 - 2: with dual certificates

- ① Information-preservation guarantees:
a RIP analysis
- ② Total variation regularization:
a dual certificate analysis
- ③ Conclusion, outlooks

①

Information-preservation guarantees: a RIP analysis

Joint work with **R. Gribonval, G. Blanchard, Y. Traonmilin**

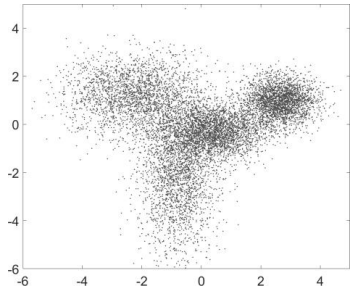
②

Total variation regularization: a dual certificate analysis

③

Conclusion, outlooks

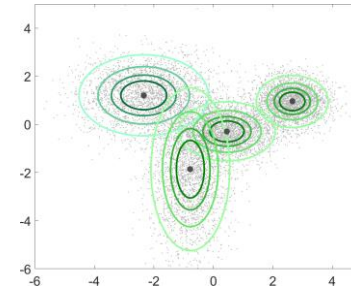
Recall: Linear inverse problem



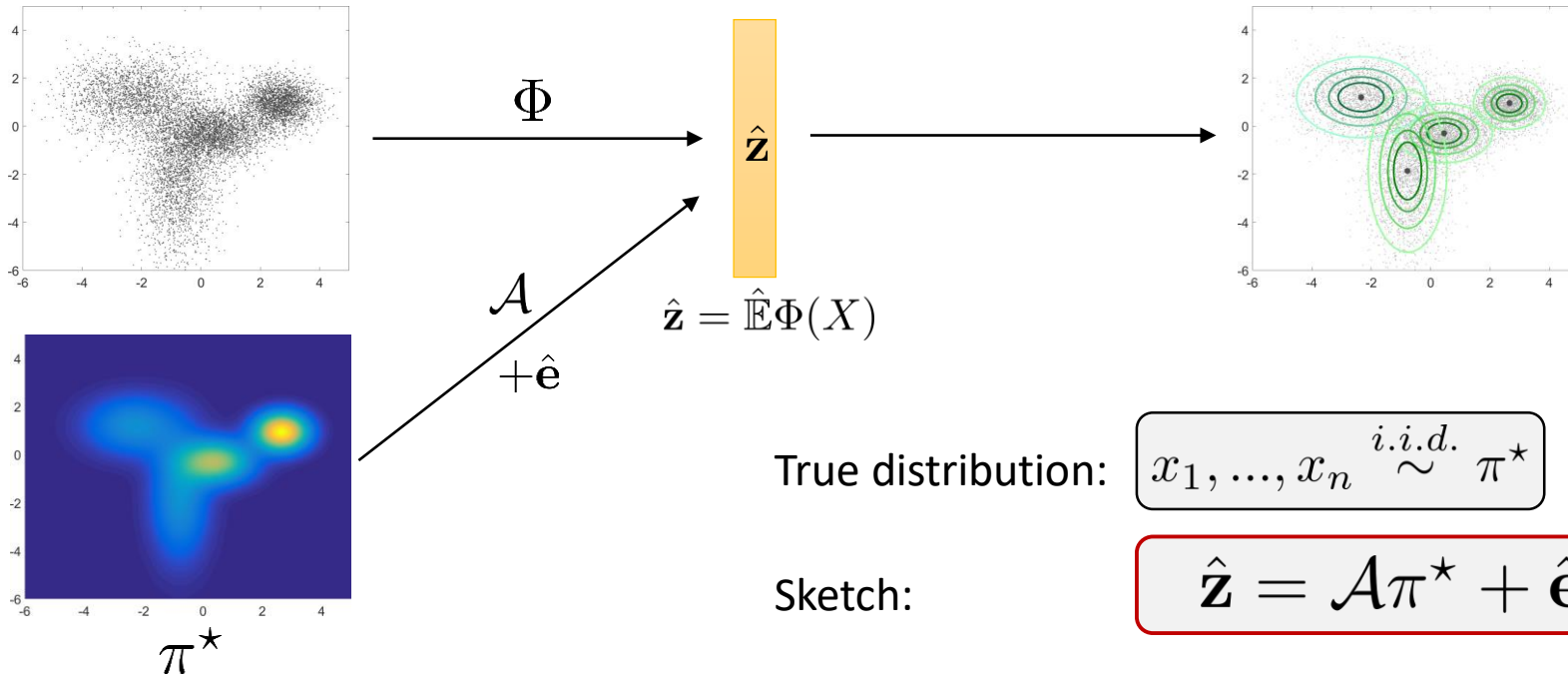
Φ

$\hat{\mathbf{z}}$

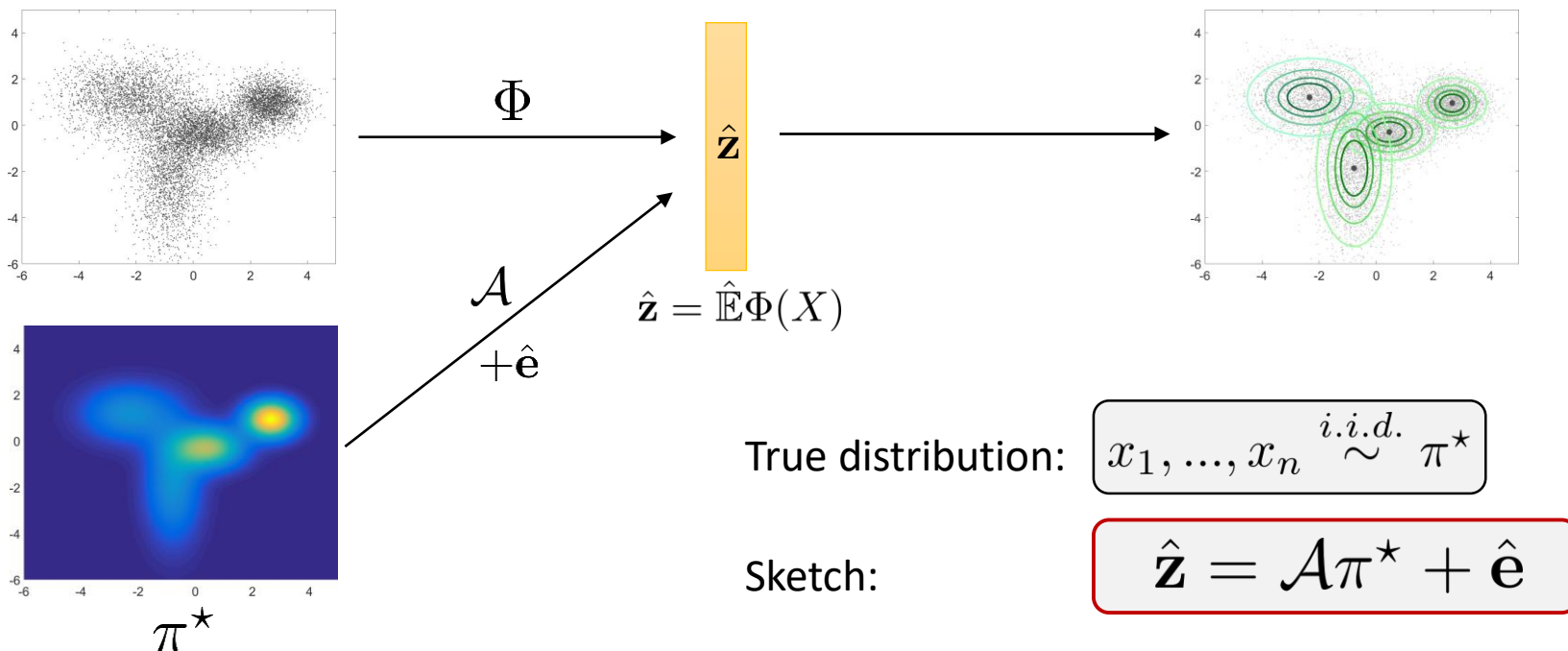
$$\hat{\mathbf{z}} = \hat{\mathbb{E}}\Phi(X)$$



Recall: Linear inverse problem

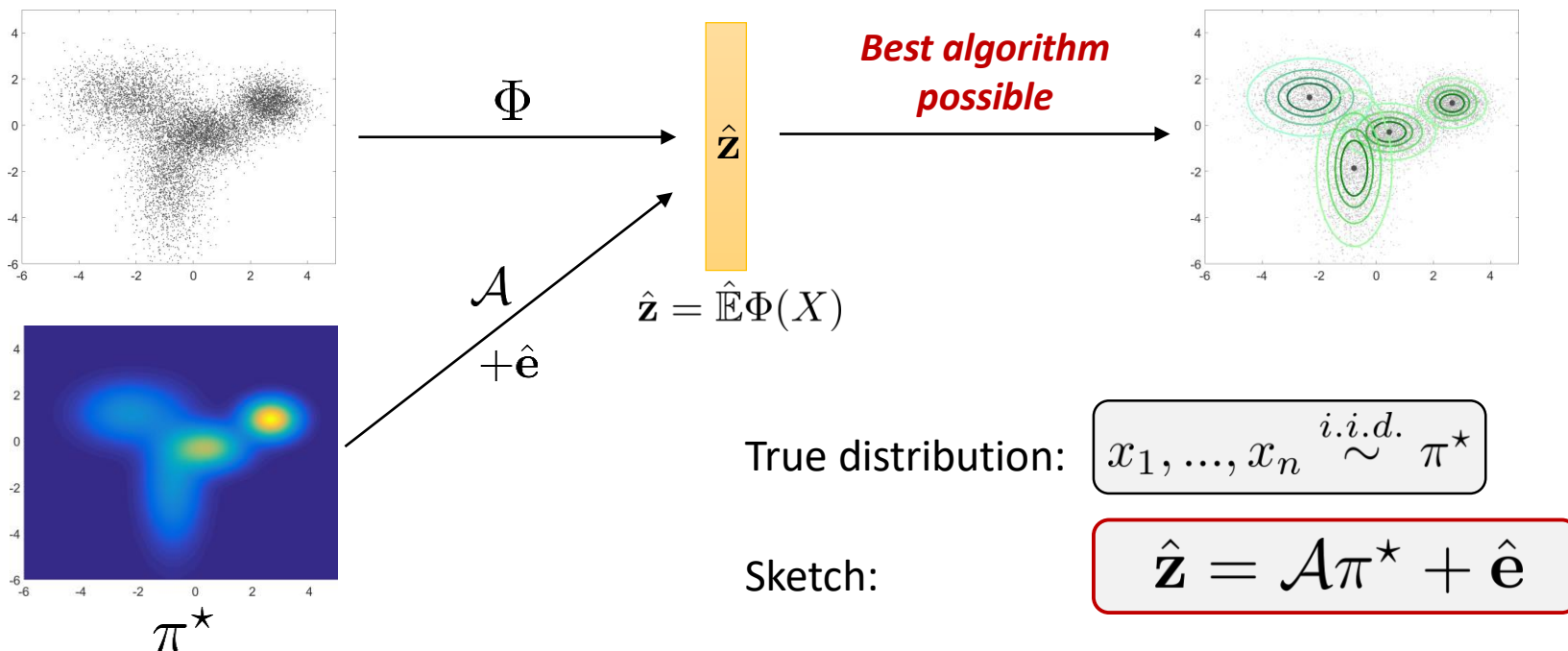


Recall: Linear inverse problem



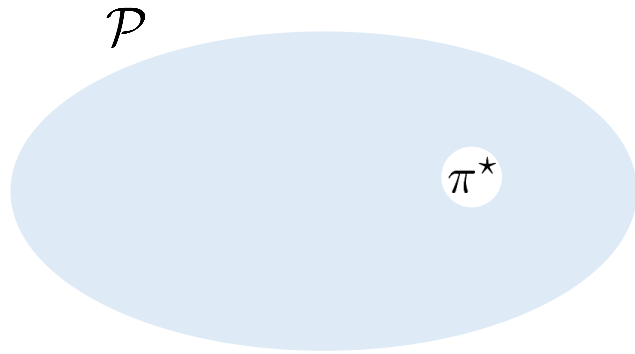
- Estimation problem = **linear inverse problem** on measures
- **Extremely ill-posed !**

Recall: Linear inverse problem

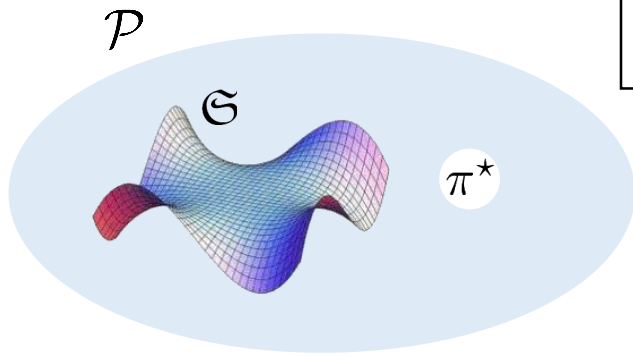


- Estimation problem = **linear inverse problem** on measures
- **Extremely ill-posed !**
- **Feasibility?** (*information-preservation*)

Information preservation guarantees

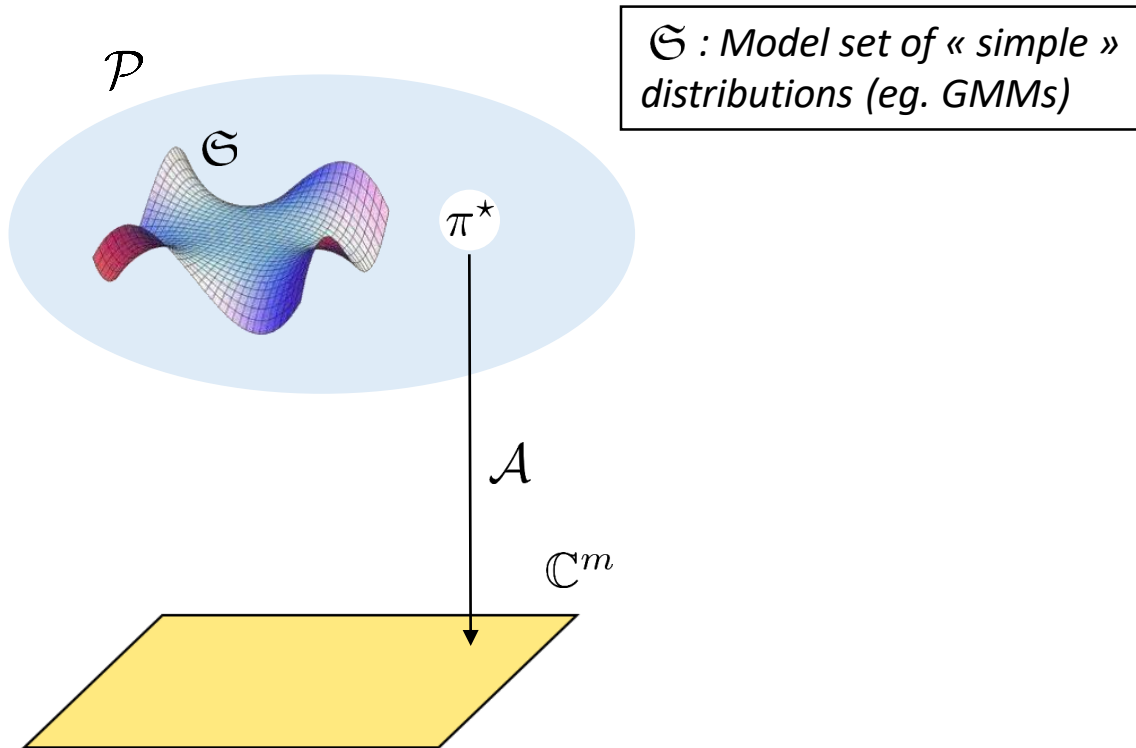


Information preservation guarantees

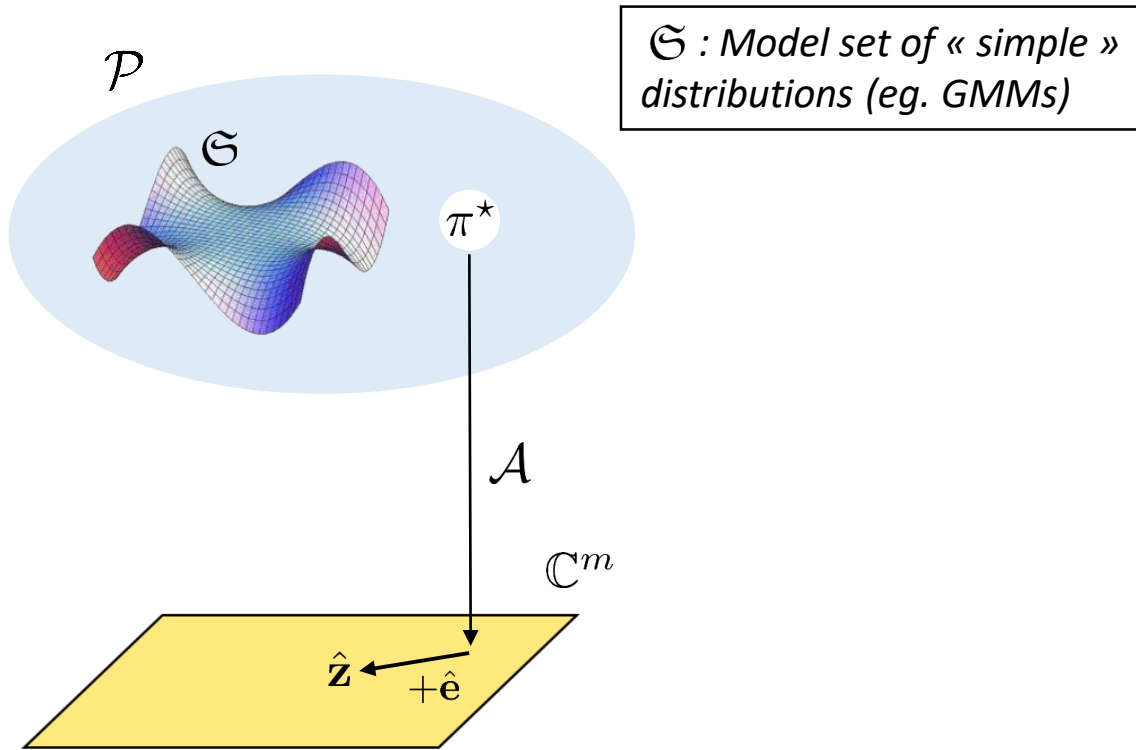


\mathcal{S} : Model set of « simple » distributions (eg. GMMs)

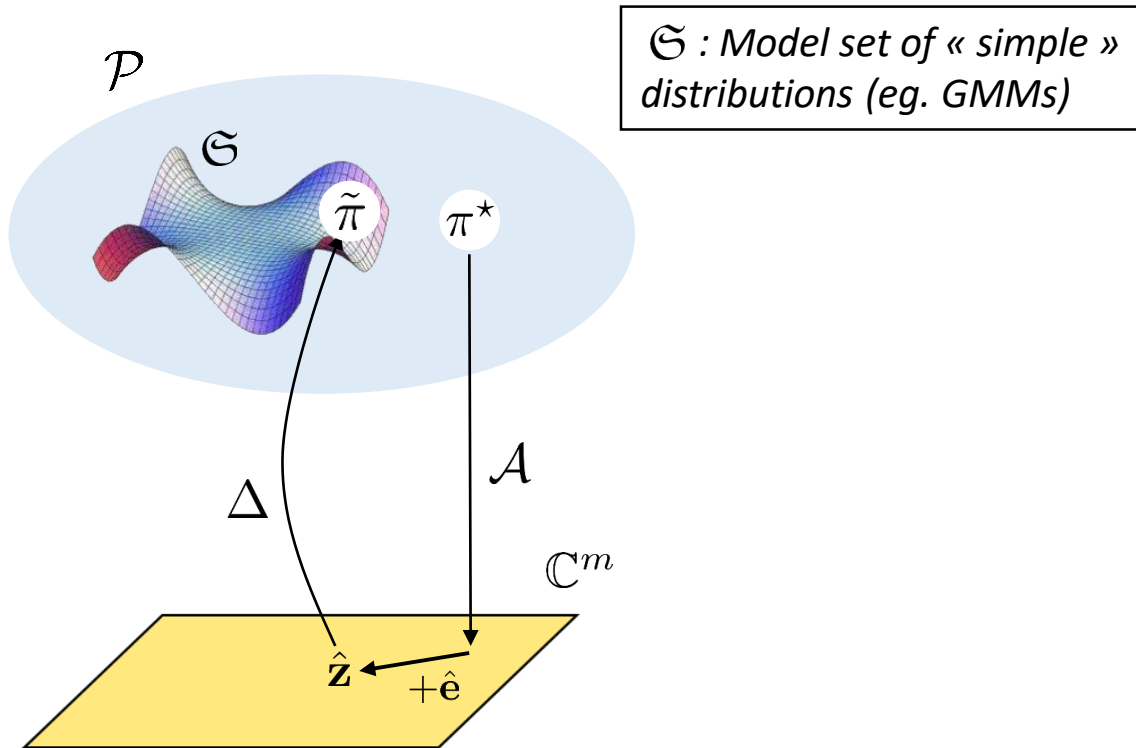
Information preservation guarantees



Information preservation guarantees



Information preservation guarantees

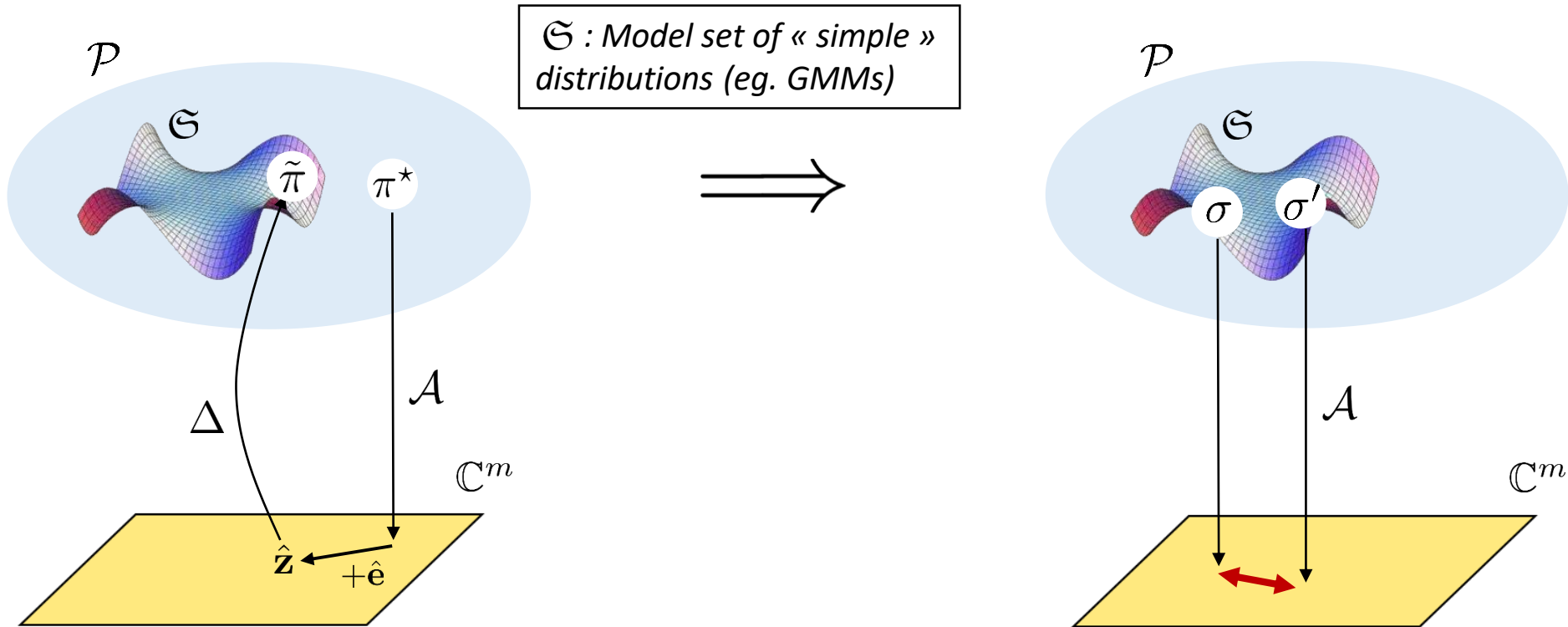


Goal

Prove the existence of a *decoder* Δ robust to **noise** and stable to **modeling error**.

« Instance-optimal » decoder

Information preservation guarantees



Goal

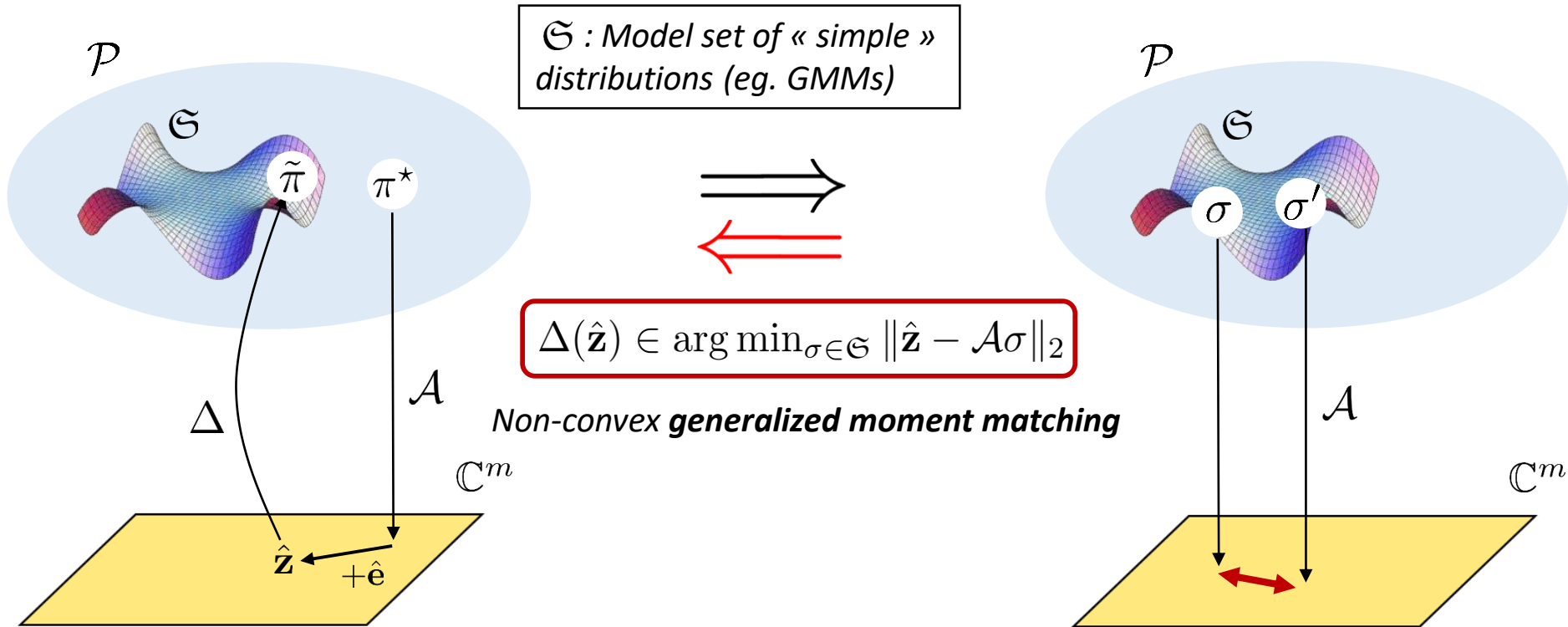
Prove the existence of a *decoder* Δ robust to **noise** and stable to **modeling error**.

« Instance-optimal » decoder

Lower Restricted Isometry Property

$$\|\sigma - \sigma'\| \lesssim \|A\sigma - A\sigma'\|_2$$

Information preservation guarantees



Goal

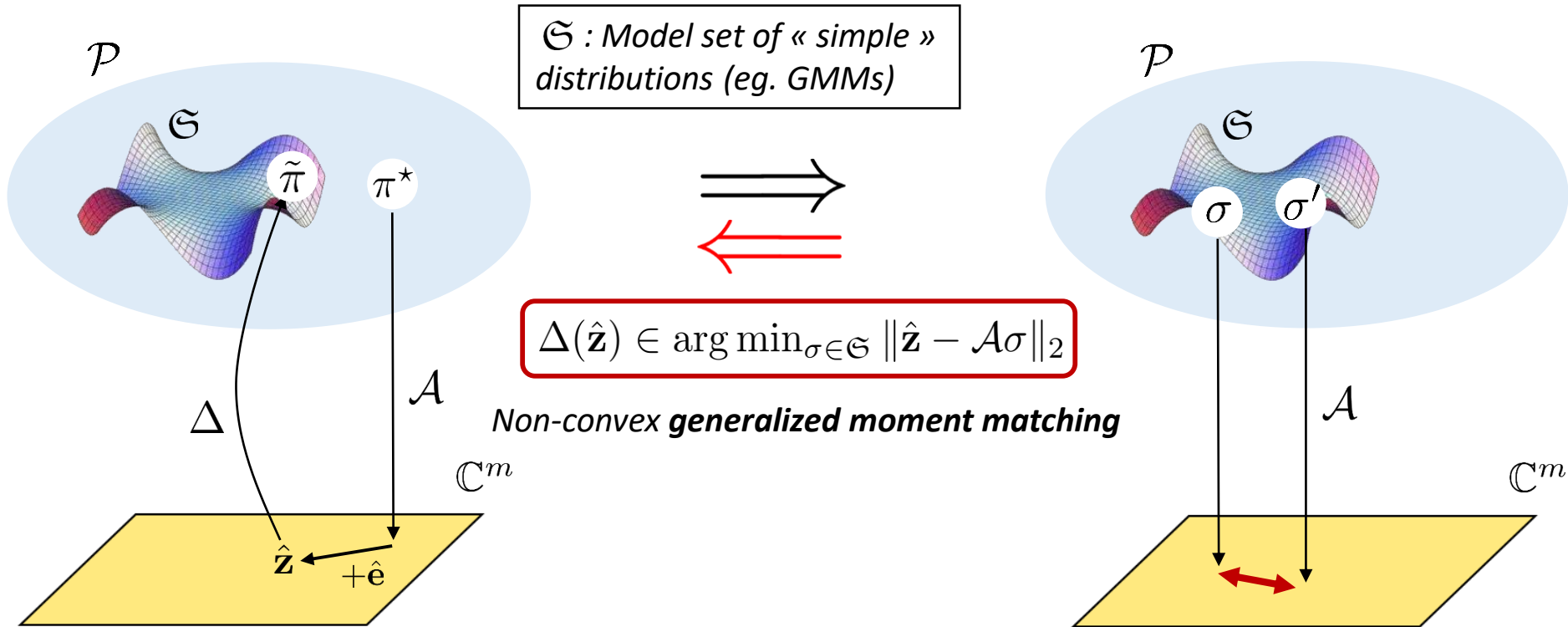
Prove the existence of a *decoder* Δ robust to **noise** and stable to **modeling error**.

« Instance-optimal » decoder

Lower Restricted Isometry Property

$$\|\sigma - \sigma'\| \lesssim \|\mathcal{A}\sigma - \mathcal{A}\sigma'\|_2$$

Information preservation guarantees



Goal

Prove the existence of a *decoder* Δ robust to **noise** and stable to **modeling error**.

« Instance-optimal » decoder

Lower Restricted Isometry Property

$$\|\sigma - \sigma'\| \lesssim \|\mathcal{A}\sigma - \mathcal{A}\sigma'\|_2$$

New goal: find/construct models \mathcal{G} and operators \mathcal{A} that satisfy the LRIP (w.h.p.)

Appropriate metric

Goal: LRIP w.h.p. on \mathcal{A} , $\forall \sigma, \sigma' \in \mathfrak{S}$, $\|\sigma - \sigma'\| \lesssim \|\mathcal{A}\sigma - \mathcal{A}\sigma'\|_2$.

Appropriate metric

Goal: LRIP w.h.p. on \mathcal{A} , $\forall \sigma, \sigma' \in \mathfrak{S}$, $\|\sigma - \sigma'\| \lesssim \|\mathcal{A}\sigma - \mathcal{A}\sigma'\|_2$.

Reproducing kernel:

$$\kappa(x, x') \quad \langle \text{blue bar}, \text{orange bar} \rangle$$

Appropriate metric

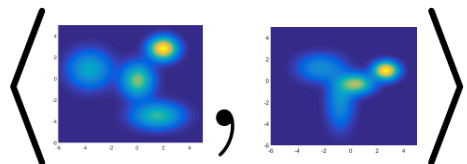
Goal: LRIP w.h.p. on \mathcal{A} , $\forall \sigma, \sigma' \in \mathfrak{G}$, $\|\sigma - \sigma'\| \lesssim \|\mathcal{A}\sigma - \mathcal{A}\sigma'\|_2$.

Reproducing kernel:

$$\kappa(x, x') \quad \left\langle \begin{array}{|c|} \hline \text{blue bar} \\ \hline \end{array}, \begin{array}{|c|} \hline \text{orange bar} \\ \hline \end{array} \right\rangle$$

Kernel mean

$$\kappa(\pi, \pi') = \mathbb{E}\kappa(X, X')$$



Appropriate metric

Goal: LRIP w.h.p. on \mathcal{A} , $\forall \sigma, \sigma' \in \mathfrak{S}$, $\|\sigma - \sigma'\| \lesssim \|\mathcal{A}\sigma - \mathcal{A}\sigma'\|_2$.

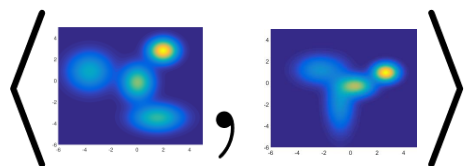
Reproducing kernel:

$$\kappa(x, x') \quad \left\langle \begin{array}{|c|} \hline \text{blue bar} \\ \hline \end{array}, \begin{array}{|c|} \hline \text{orange bar} \\ \hline \end{array} \right\rangle$$

Φ : random features [Rahimi2007]
to approximate κ

Kernel mean

$$\kappa(\pi, \pi') = \mathbb{E}\kappa(X, X')$$



Appropriate metric

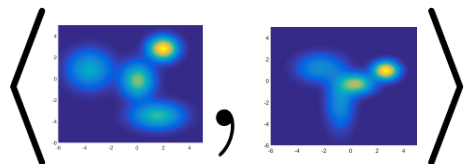
Goal: LRIP w.h.p. on \mathcal{A} , $\forall \sigma, \sigma' \in \mathfrak{S}$, $\|\sigma - \sigma'\| \lesssim \|\mathcal{A}\sigma - \mathcal{A}\sigma'\|_2$.

Reproducing kernel:

$$\kappa(x, x') \quad \left\langle \begin{array}{|c|} \hline \text{blue bar} \\ \hline \end{array}, \begin{array}{|c|} \hline \text{orange bar} \\ \hline \end{array} \right\rangle$$

Kernel mean

$$\kappa(\pi, \pi') = \mathbb{E}\kappa(X, X')$$



Φ : random features [Rahimi2007]
to approximate κ

$$\mathcal{A}\pi = \mathbb{E}_\pi \Phi(X)$$

Basis for LRIP

$$\|\pi - \pi'\|_\kappa^2 \approx \|\mathcal{A}\pi - \mathcal{A}\pi'\|_2^2$$

Proof strategy (1)

Reformulation of the LRIP

Goal: LRIP $\|\sigma - \sigma'\|_{\kappa} \lesssim \|\mathcal{A}(\sigma - \sigma')\|_2$

Proof strategy (1)

Reformulation of the LRIP

Goal: LRIP $\|\sigma - \sigma'\|_{\kappa} \lesssim \|\mathcal{A}(\sigma - \sigma')\|_2$

$$\Leftrightarrow 1 \lesssim \left\| \mathcal{A}\left(\frac{\sigma - \sigma'}{\|\sigma - \sigma'\|_{\kappa}}\right) \right\|_2$$

Proof strategy (1)

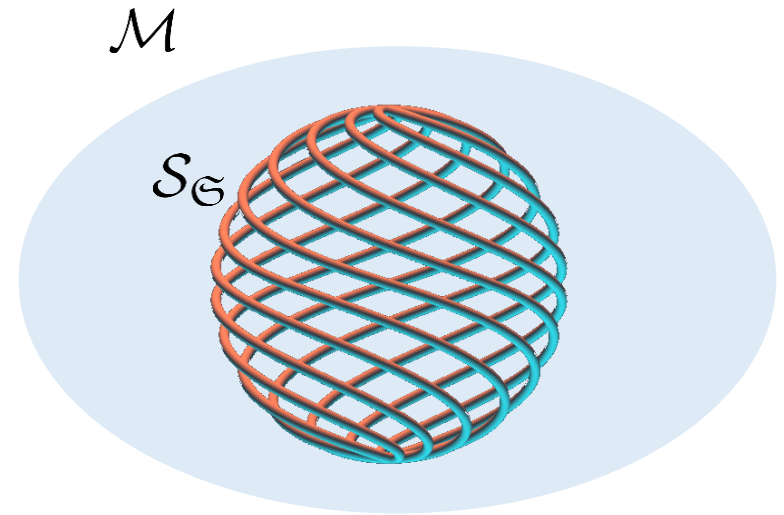
Reformulation of the LRIP

Goal: LRIP $\|\sigma - \sigma'\|_{\kappa} \lesssim \|\mathcal{A}(\sigma - \sigma')\|_2$

$$\Leftrightarrow 1 \lesssim \left\| \mathcal{A}\left(\frac{\sigma - \sigma'}{\|\sigma - \sigma'\|_{\kappa}}\right) \right\|_2$$

Definition: Normalized Secant set

$$\mathcal{S}_{\mathcal{G}} = \left\{ \frac{\sigma - \sigma'}{\|\sigma - \sigma'\|_{\kappa}}; \sigma, \sigma' \in \mathcal{G} \right\}$$



Proof strategy (1)

Reformulation of the LRIP

Goal: LRIP $\|\sigma - \sigma'\|_{\kappa} \lesssim \|\mathcal{A}(\sigma - \sigma')\|_2$

$$\Leftrightarrow 1 \lesssim \left\| \mathcal{A} \left(\frac{\sigma - \sigma'}{\|\sigma - \sigma'\|_{\kappa}} \right) \right\|_2$$

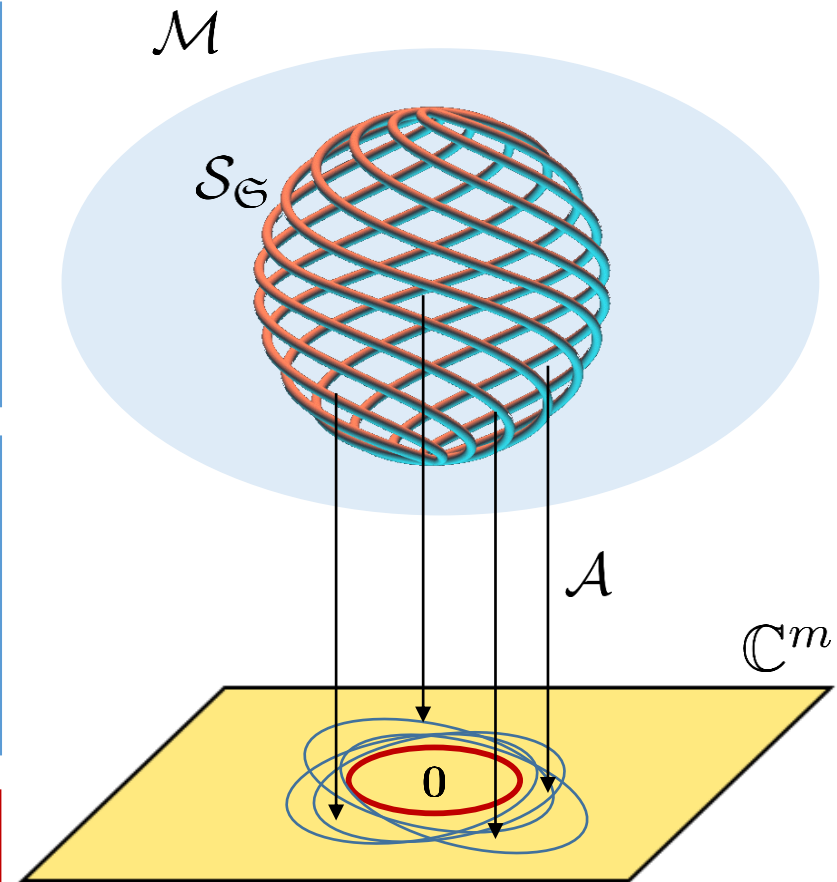
Definition: Normalized Secant set

$$\mathcal{S}_{\mathcal{G}} = \left\{ \frac{\sigma - \sigma'}{\|\sigma - \sigma'\|_{\kappa}}; \sigma, \sigma' \in \mathcal{G} \right\}$$

New goal

With high probability on \mathcal{A} :

for all $s \in \mathcal{S}_{\mathcal{G}}, 1 \lesssim \|\mathcal{A}s\|_2$.



Proof strategy (2)

Goal: LRIP w.h.p. on \mathcal{A} , $\forall s \in \mathcal{S}_{\mathcal{E}}, 1 \lesssim \|\mathcal{A}s\|_2$.

Proof strategy (2)

Goal: LRIP w.h.p. on \mathcal{A} , $\forall s \in \mathcal{S}_{\mathcal{E}}, 1 \lesssim \|\mathcal{A}s\|_2$.

① Pointwise LRIP:
Concentration inequality $\forall s$, w.h.p. on \mathcal{A} , LRIP.

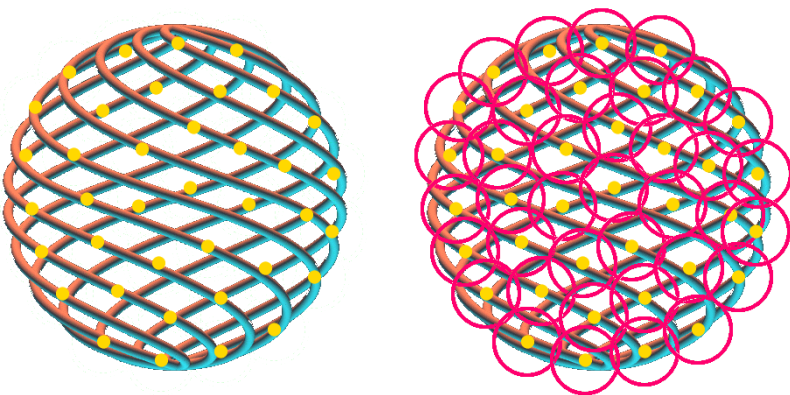
Proof strategy (2)

Goal: LRIP w.h.p. on \mathcal{A} , $\forall s \in \mathcal{S}_\epsilon$, $1 \lesssim \|\mathcal{A}s\|_2$.

① Pointwise LRIP:
Concentration inequality

$\forall s$, w.h.p. on \mathcal{A} , LRIP.

② Extension to LRIP:
covering numbers



w.h.p. on \mathcal{A} , $\forall s$, LRIP.

Main hypothesis

The *normalized secant set* $\mathcal{S}(\mathfrak{S})$ has finite covering numbers.

Main result

Main hypothesis

The *normalized secant set* $\mathcal{S}(\mathfrak{S})$ has finite covering numbers.

Result

For $m \geq C \times \log(\text{cov. num.})$,

Main result

Main hypothesis

The *normalized secant set* $\mathcal{S}(\mathfrak{S})$ has finite covering numbers.

Result

For $m \geq C \times \log(\text{cov. num.})$,

Quality of pointwise LRIP

Dimensionality of the model

Main hypothesis

The *normalized secant set* $\mathcal{S}(\mathfrak{S})$ has finite covering numbers.

Result

For $m \geq C \times \log(\text{cov. num.})$,

Quality of pointwise LRIP

Dimensionality of the model

W.h.p.

$$\|\pi^* - \Delta(\hat{\mathbf{z}})\| \leq d(\pi^*, \mathfrak{S}) + \mathcal{O}(1/\sqrt{n})$$

Main result

Main hypothesis

The *normalized secant set* $\mathcal{S}(\mathfrak{S})$ has finite covering numbers.

Result

For $m \geq C \times \log(\text{cov. num.})$,

Quality of pointwise LRIP

Dimensionality of the model

W.h.p.

Modeling error

Empirical noise

$$\|\pi^* - \Delta(\hat{\mathbf{z}})\| \leq d(\pi^*, \mathfrak{S}) + \mathcal{O}(1/\sqrt{n})$$

Main result

Main hypothesis

The *normalized secant set* $\mathcal{S}(\mathfrak{S})$ has finite covering numbers.

Result

For $m \geq C \times \log(\text{cov. num.})$,

Quality of pointwise LRIP

Dimensionality of the model

W.h.p.

Modeling error

Empirical noise

$$\|\pi^* - \Delta(\hat{\mathbf{z}})\| \leq d(\pi^*, \mathfrak{S}) + \mathcal{O}(1/\sqrt{n})$$

- **Classic Compressive Sensing:** finite dimension: **Known**
- **Here:** infinite dimension: **Technical**

k-means with mixtures of Diracs

k-means with mixtures of Diracs

Hypotheses

- ε - separated centroids
- M - bounded domain for centroids

Application

k-means with mixtures of Diracs

Hypotheses

*(no assumption
on the **data**)*

- ε - separated centroids
- M - bounded domain for centroids

Application

k-means with mixtures of Diracs

Hypotheses

*(no assumption
on the **data**)*

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features *(for technical reasons)*

Application

k-means with mixtures of Diracs

Hypotheses

(no assumption
on the **data**)

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features (for technical reasons)

Result

- W.r.t. k-means usual cost (SSE)

Application

k-means with mixtures of Diracs

Hypotheses

(no assumption
on the **data**)

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features (for technical reasons)

Result

- W.r.t. k-means usual cost (SSE)

Sketch size

$$m \geq \mathcal{O}(k^2 d \cdot \text{polylog}(k, d) \log(M/\varepsilon))$$

Application

k-means with mixtures of Diracs

Hypotheses

(no assumption
on the **data**)

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features (for technical reasons)

Result

- W.r.t. k-means usual cost (SSE)

Sketch size

$$m \geq \mathcal{O}(k^2 d \cdot \text{polylog}(k, d) \log(M/\varepsilon))$$

GMM with known covariance

Application

k-means with mixtures of Diracs

Hypotheses

(no assumption
on the **data**)

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features (for technical reasons)

Result

- W.r.t. k-means usual cost (SSE)

Sketch size

$$m \geq \mathcal{O}(k^2 d \cdot \text{polylog}(k, d) \log(M/\varepsilon))$$

GMM with known covariance

Hypotheses

- **Sufficiently** separated means
- Bounded domain for means

Application

k-means with mixtures of Diracs

Hypotheses

(no assumption
on the **data**)

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features (for technical reasons)

Result

- W.r.t. k-means usual cost (SSE)

Sketch size

$$m \geq \mathcal{O}(k^2 d \cdot \text{polylog}(k, d) \log(M/\varepsilon))$$

GMM with known covariance

Hypotheses

- **Sufficiently** separated means
- Bounded domain for means

Sketch

- Fourier features

Application

k-means with mixtures of Diracs

Hypotheses

(no assumption
on the **data**)

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features (for technical reasons)

Result

- W.r.t. k-means usual cost (SSE)

Sketch size

$$m \geq \mathcal{O}(k^2 d \cdot \text{polylog}(k, d) \log(M/\varepsilon))$$

GMM with known covariance

Hypotheses

- **Sufficiently** separated means
- Bounded domain for means

Sketch

- Fourier features

Result

- With respect to **log-likelihood**

Application

k-means with mixtures of Diracs

Hypotheses

(no assumption
on the **data**)

- ε - separated centroids
- M - bounded domain for centroids

Sketch

- *Adjusted* Random Fourier features (for technical reasons)

Result

- W.r.t. k-means usual cost (SSE)

Sketch size

$$m \geq \mathcal{O}(k^2 d \cdot \text{polylog}(k, d) \log(M/\varepsilon))$$

GMM with known covariance

Hypotheses

- **Sufficiently** separated means
- Bounded domain for means

Sketch

- Fourier features

Result

- With respect to **log-likelihood**

Sketch size

$$m \geq \mathcal{O}(k^2 d \cdot \text{polylog}(k, d))$$

Summary

With the RIP analysis:

Summary

With the RIP analysis:

- **Moment matching:** best decoder possible (instance optimal)
 - Information-preservation guarantees

Summary

With the RIP analysis:

- **Moment matching:** best decoder possible (instance optimal)
 - Information-preservation guarantees
- Fine control on modeling error, noise, and metrics
 - **Can incorporate k-means cost or log-likelihood**

Summary

With the RIP analysis:

- **Moment matching:** best decoder possible (instance optimal)
 - Information-preservation guarantees
- Fine control on modeling error, noise, and metrics
 - **Can incorporate k-means cost or log-likelihood**

Compressive Sensing:

Summary

With the RIP analysis:

- **Moment matching:** best decoder possible (instance optimal)
 - Information-preservation guarantees
- Fine control on modeling error, noise, and metrics
 - **Can incorporate k-means cost or log-likelihood**

Compressive Sensing:

- Random, dimensionality-reducing operator



Summary

With the RIP analysis:

- **Moment matching:** best decoder possible (instance optimal)
 - Information-preservation guarantees
- Fine control on modeling error, noise, and metrics
 - **Can incorporate k-means cost or log-likelihood**

Compressive Sensing:

- Random, dimensionality-reducing operator ✓
- Sparsity ✓

Summary

With the RIP analysis:

- **Moment matching:** best decoder possible (instance optimal)
 - Information-preservation guarantees
- Fine control on modeling error, noise, and metrics
 - **Can incorporate k-means cost or log-likelihood**

Compressive Sensing:

- Random, dimensionality-reducing operator ✓
- Sparsity ✓
- The information is preserved ✓

Summary

With the RIP analysis:

- **Moment matching:** best decoder possible (instance optimal)
 - Information-preservation guarantees
- Fine control on modeling error, noise, and metrics
 - **Can incorporate k-means cost or log-likelihood**

Compressive Sensing:

- Random, dimensionality-reducing operator ✓
- Sparsity ✓
- The information is preserved ✓
- **Convex relaxation?** ✗

①

Information-preservation guarantees:
a RIP analysis

②

Total variation regularization:
a dual certificate analysis
Joint work with **C. Poon**, **G. Peyré**

③

Conclusion, outlooks

Total Variation regularization

Previously: RIP analysis

Minimization: moment matching

$$\min_{\theta} \left\| \mathcal{A} \left(\sum w_i \pi_{\theta_i} \right) - \hat{\mathbf{z}} \right\|_2$$

Total Variation regularization

Previously: RIP analysis

Minimization: moment matching

$$\min_{\theta} \left\| \mathcal{A} \left(\sum w_i \pi_{\theta_i} \right) - \hat{\mathbf{z}} \right\|_2$$

- Must know k
- **Non-convex !**

Total Variation regularization

Previously: RIP analysis

Minimization: moment matching

$$\min_{\theta} \left\| \mathcal{A} \left(\sum w_i \pi_{\theta_i} \right) - \hat{\mathbf{z}} \right\|_2$$

- Must know k
- **Non-convex !**

Convex relaxation (« *super resolution* »)

$$\min_{\mu} \frac{1}{2} \left\| \Psi \mu - \hat{\mathbf{z}} \right\|_2 + \lambda \left\| \mu \right\|_{\text{TV}}$$

- μ : Radon measure
- $\Psi \mu = \int (\mathcal{A} \pi_{\theta}) d\mu(\theta)$
- $\left\| \cdot \right\|_{\text{TV}}$: Total variation (« L1 norm »)

Total Variation regularization

Previously: RIP analysis

Minimization: moment matching

$$\min_{\theta} \left\| \mathcal{A} \left(\sum w_i \pi_{\theta_i} \right) - \hat{\mathbf{z}} \right\|_2$$

- Must know k
- **Non-convex !**

Convex relaxation (« super resolution »)

$$\min_{\mu} \frac{1}{2} \left\| \Psi \mu - \hat{\mathbf{z}} \right\|_2 + \lambda \left\| \mu \right\|_{\text{TV}}$$

- μ : Radon measure
- $\Psi \mu = \int (\mathcal{A} \pi_{\theta}) d\mu(\theta)$
- $\| \cdot \|_{\text{TV}}$: Total variation (« L1 norm »)

Convex:

- can be handled by eg Frank-Wolfe algorithm [Boyd 2015], or in some cases as a SDP

Total Variation regularization

Previously: RIP analysis

Minimization: moment matching

$$\min_{\theta} \left\| \mathcal{A} \left(\sum w_i \pi_{\theta_i} \right) - \hat{\mathbf{z}} \right\|_2$$

- Must know k
- **Non-convex !**

Convex relaxation (« super resolution »)

$$\min_{\mu} \frac{1}{2} \left\| \Psi \mu - \hat{\mathbf{z}} \right\|_2 + \lambda \left\| \mu \right\|_{\text{TV}}$$

- μ : Radon measure
- $\Psi \mu = \int (\mathcal{A} \pi_{\theta}) d\mu(\theta)$
- $\| \cdot \|_{\text{TV}}$: Total variation (« L1 norm »)

Convex:

- can be handled by eg Frank-Wolfe algorithm [Boyd 2015], or in some cases as a SDP

Questions:

- Is the measure μ sparse? $\mu = \sum \tilde{w}_i \delta_{\tilde{\theta}_i}$
- Does it have the right number of components?
- Does it recover the true w_i, θ_i ?

A bit of convex analysis

Intuition: first order conditions: μ_0 solution $\iff \frac{1}{\lambda} \Psi^*(\Psi\mu_0 - \hat{\mathbf{z}}) \in \partial\|\mu_0\|_{\text{TV}}$

A bit of convex analysis

Intuition: first order conditions: μ_0 solution $\iff \frac{1}{\lambda} \Psi^*(\Psi\mu_0 - \hat{\mathbf{z}}) \in \partial\|\mu_0\|_{\text{TV}}$

Def. : Dual certificate (= Lagrange multiplier in the noiseless case...)

$$\eta \in \text{Im}(\Psi^*) \cap \partial\|\mu_0\|_{\text{TV}}$$

A bit of convex analysis

Intuition: first order conditions: μ_0 solution $\iff \frac{1}{\lambda} \Psi^*(\Psi \mu_0 - \hat{\mathbf{z}}) \in \partial \|\mu_0\|_{\text{TV}}$

Def. : Dual certificate (= Lagrange multiplier in the noiseless case...)

$$\eta \in \text{Im}(\Psi^*) \cap \partial \|\mu_0\|_{\text{TV}}$$

What is a dual certificate?

A bit of convex analysis

Intuition: first order conditions: μ_0 solution $\iff \frac{1}{\lambda} \Psi^*(\Psi\mu_0 - \hat{\mathbf{z}}) \in \partial\|\mu_0\|_{\text{TV}}$

Def. : Dual certificate (= Lagrange multiplier in the noiseless case...)

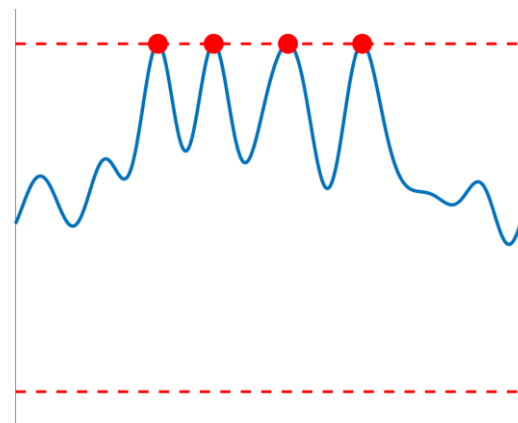
$$\eta \in \text{Im}(\Psi^*) \cap \partial\|\mu_0\|_{\text{TV}}$$

What is a dual certificate?

$$\eta(\theta) = \langle \mathbf{h}, \mathcal{A}\pi_\theta \rangle$$

Such that:

- $\eta(\theta_i) = 1$
- $|\eta(\theta)| < 1$ otherwise
- $\nabla^2\eta(\theta_i) \prec 0$



A bit of convex analysis

Intuition: first order conditions: μ_0 solution $\iff \frac{1}{\lambda} \Psi^*(\Psi\mu_0 - \hat{\mathbf{z}}) \in \partial\|\mu_0\|_{\text{TV}}$

Def. : Dual certificate (= Lagrange multiplier in the noiseless case...)

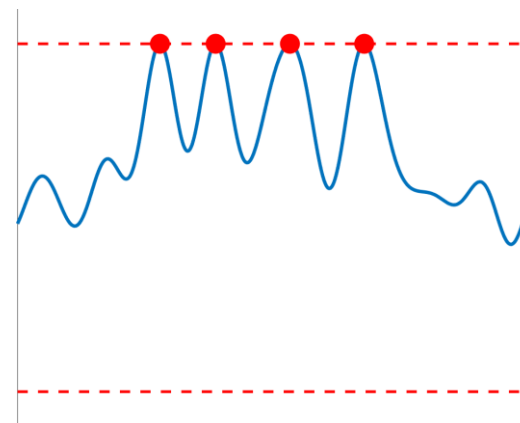
$$\eta \in \text{Im}(\Psi^*) \cap \partial\|\mu_0\|_{\text{TV}}$$

What is a dual certificate?

$$\eta(\theta) = \langle \mathbf{h}, \mathcal{A}\pi_\theta \rangle$$

Such that:

- $\eta(\theta_i) = 1$
- $|\eta(\theta)| < 1$ otherwise
- $\nabla^2\eta(\theta_i) \prec 0$



Ensures uniqueness and robustness...

Strategy: going back to random features

Step 1: study full kernel

Strategy: going back to random features

Step 1: study full kernel

$$\bar{\eta} \in \text{Span} \{ \kappa(\theta_i, \cdot), \partial_1 \kappa(\theta_i, \cdot) \} \subset \text{Im}(\mathbb{E} \Psi^*)$$

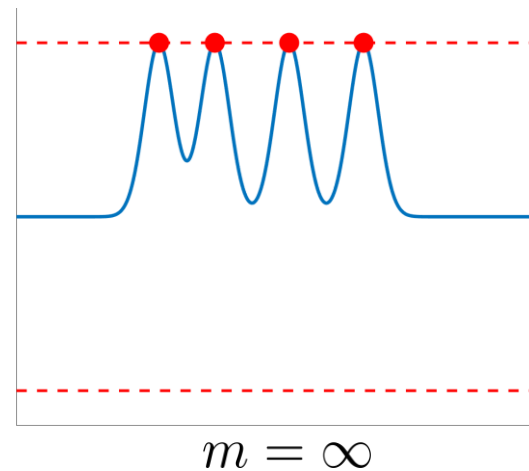
Strategy: going back to random features

Step 1: study full kernel

$$\bar{\eta} \in \text{Span} \{ \kappa(\theta_i, \cdot), \partial_1 \kappa(\theta_i, \cdot) \} \subset \text{Im}(\mathbb{E} \Psi^*)$$

Assumptions:

- Kernel « well-behaved »
- θ_i sufficiently separated



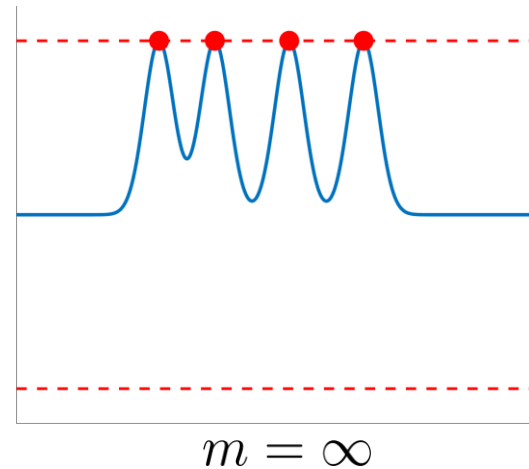
Strategy: going back to random features

Step 1: study full kernel

$$\bar{\eta} \in \text{Span} \{ \kappa(\theta_i, \cdot), \partial_1 \kappa(\theta_i, \cdot) \} \subset \text{Im}(\mathbb{E}\Psi^*)$$

Assumptions:

- Kernel « well-behaved »
- θ_i sufficiently separated



Step 2: bounding the deviations

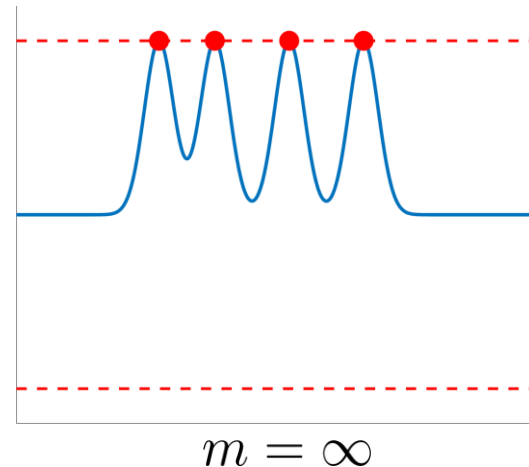
Strategy: going back to random features

Step 1: study full kernel

$$\bar{\eta} \in \text{Span} \{ \kappa(\theta_i, \cdot), \partial_1 \kappa(\theta_i, \cdot) \} \subset \text{Im}(\mathbb{E} \Psi^*)$$

Assumptions:

- Kernel « well-behaved »
- θ_i sufficiently separated



Step 2: bounding the deviations

- Pointwise deviation (concentration ineq.)
- Covering numbers

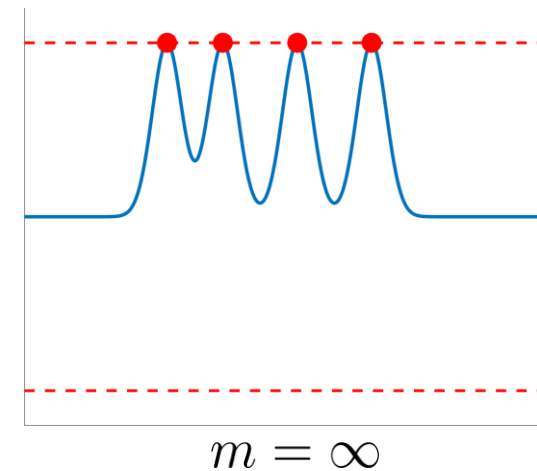
Strategy: going back to random features

Step 1: study full kernel

$$\bar{\eta} \in \text{Span} \{ \kappa(\theta_i, \cdot), \partial_1 \kappa(\theta_i, \cdot) \} \subset \text{Im}(\mathbb{E} \Psi^*)$$

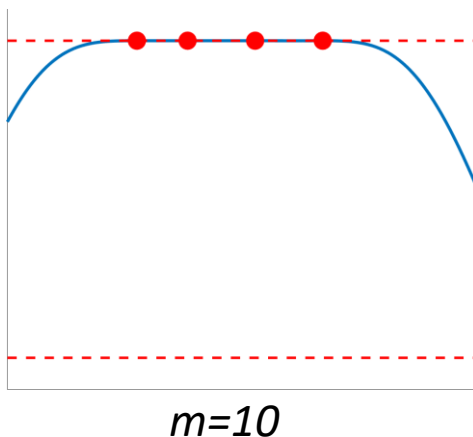
Assumptions:

- Kernel « well-behaved »
- θ_i sufficiently separated



Step 2: bounding the deviations

- Pointwise deviation (concentration ineq.)
- Covering numbers



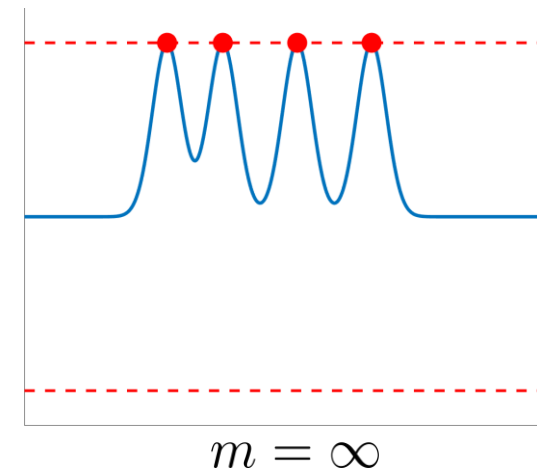
Strategy: going back to random features

Step 1: study full kernel

$$\bar{\eta} \in \text{Span} \{ \kappa(\theta_i, \cdot), \partial_1 \kappa(\theta_i, \cdot) \} \subset \text{Im}(\mathbb{E} \Psi^*)$$

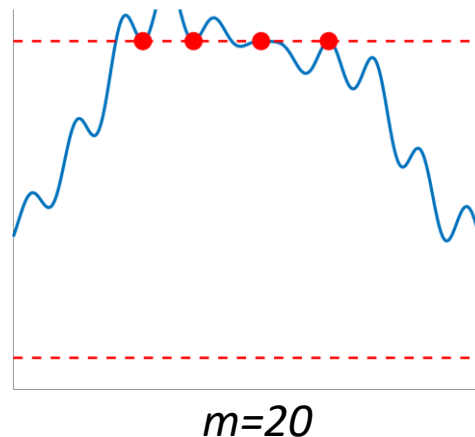
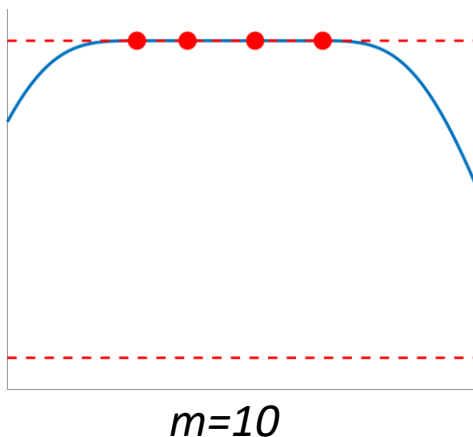
Assumptions:

- Kernel « well-behaved »
- θ_i sufficiently separated



Step 2: bounding the deviations

- Pointwise deviation (concentration ineq.)
- Covering numbers



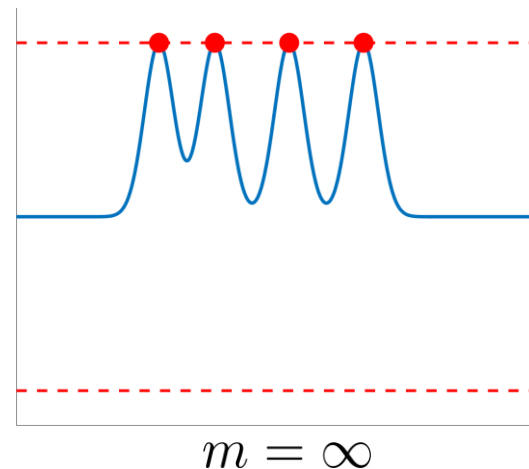
Strategy: going back to random features

Step 1: study full kernel

$$\bar{\eta} \in \text{Span} \{ \kappa(\theta_i, \cdot), \partial_1 \kappa(\theta_i, \cdot) \} \subset \text{Im}(\mathbb{E} \Psi^*)$$

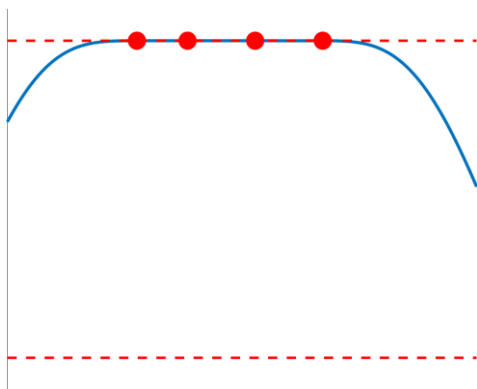
Assumptions:

- Kernel « well-behaved »
- θ_i sufficiently separated

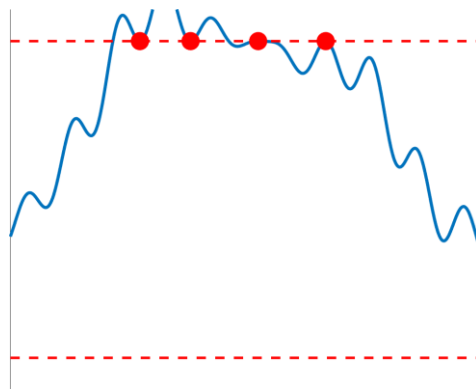


Step 2: bounding the deviations

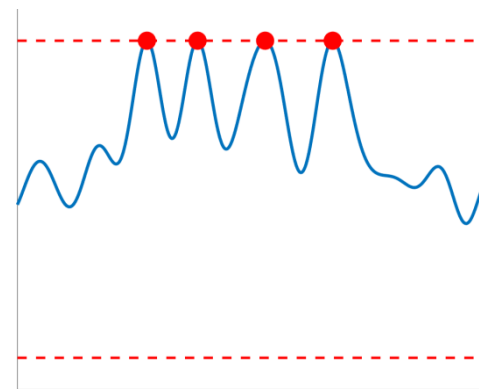
- Pointwise deviation (concentration ineq.)
- Covering numbers



$m=10$



$m=20$



$m=50$

Results for separated GMM

Assumption: data are *actually* drawn from a GMM...

1: Ideal scaling in sparsity

Results for separated GMM

Assumption: data are *actually* drawn from a GMM...

1: Ideal scaling in sparsity

$$m \geq \mathcal{O}(kd^4 \cdot \text{polylog}(k, d))$$

Results for separated GMM

Assumption: data are *actually* drawn from a GMM...

1: Ideal scaling in sparsity

$$m \geq \mathcal{O}(kd^4 \cdot \text{polylog}(k, d))$$

↑
In progress...

Results for separated GMM

Assumption: data are *actually* drawn from a GMM...

1: Ideal scaling in sparsity

$$m \geq \mathcal{O}(kd^4 \cdot \text{polylog}(k, d))$$

↑
In progress...

- $\tilde{\mu}$ *not necessarily sparse*, but:
- Mass of $\tilde{\mu}$ concentrated around true θ_i
- *Proof*: infinite-dimensional golfing scheme (new)

Results for separated GMM

Assumption: data are *actually* drawn from a GMM...

1: Ideal scaling in sparsity

$$m \geq \mathcal{O}(kd^4 \cdot \text{polylog}(k, d))$$

↑
In progress...

- $\tilde{\mu}$ *not necessarily sparse*, but:
- Mass of $\tilde{\mu}$ concentrated around true θ_i
- *Proof*: infinite-dimensional golfing scheme (new)

2: Minimal norm certificate

[Duval, Peyré 2015]

$$m \geq \mathcal{O}(k^2 d^3 \cdot \text{polylog}(k, d))$$

↑
In progress...

Results for separated GMM

Assumption: data are *actually* drawn from a GMM...

1: Ideal scaling in sparsity

$$m \geq \mathcal{O}(kd^4 \cdot \text{polylog}(k, d))$$

↑
In progress...

- $\tilde{\mu}$ *not necessarily sparse*, but:
- Mass of $\tilde{\mu}$ concentrated around true θ_i
- *Proof*: infinite-dimensional golfing scheme (new)

2: Minimal norm certificate

[Duval, Peyré 2015]

$$m \geq \mathcal{O}(k^2 d^3 \cdot \text{polylog}(k, d))$$

↑
In progress...

- when n high enough: $\tilde{\mu}$ **sparse, with right number of components**
- $\tilde{\theta}_i \xrightarrow{n \rightarrow \infty} \theta_i$
- Proof: adaptation of [Tang, Recht 2013] (*constructive!*)

①

Information-preservation guarantees:
a RIP analysis

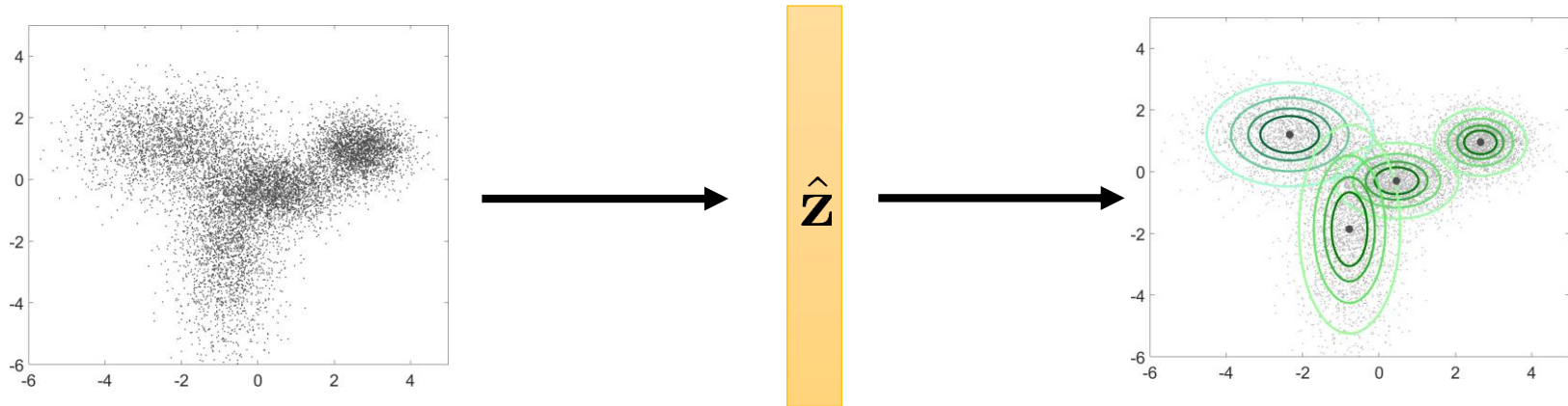
②

Total variation regularization:
a dual certificate analysis

③

Conclusion, outlooks

Sketch learning



- Sketching :
 - Streaming, distributed learning
 - Original view on data compression and generalized moments
 - Combines random features and kernel mean with infinite dimensional Compressive sensing

Summary, outlooks

- **RIP analysis**
 - Information preservation guarantees
 - Fine control on noise, modeling error (instance optimal decoder) and recovery metrics
 - Necessary and sufficient conditions
 - But: Non-convex minimization

Summary, outlooks

- **RIP analysis**

- Information preservation guarantees
- Fine control on noise, modeling error (instance optimal decoder) and recovery metrics
- Necessary and sufficient conditions
- But: Non-convex minimization

- **Dual certificate analysis**

- Convex minimization
- Does not handle modelling error
- In some cases, automatically guess the right number of components

Summary, outlooks

- **RIP analysis**

- Information preservation guarantees
- Fine control on noise, modeling error (instance optimal decoder) and recovery metrics
- Necessary and sufficient conditions
- But: Non-convex minimization

- **Dual certificate analysis**

- Convex minimization
- Does not handle modelling error
- In some cases, automatically guess the right number of components

- **Outlooks**

- Algorithms for TV minimization
- Other features Φ (not necessarily random...)
- Other « sketched » learning tasks
- Multilayer sketches ?

Thank you !

- Keriven, Bourrier, Gribonval, Pérez. **Sketching for Large-Scale Learning of Mixture Models** *Information & Inference: a Journal of the IMA*, 2017. <arXiv:1606.02838>
- Keriven, Tremblay, Traonmilin, Gribonval. **Compressive k-means** *ICASSP*, 2017.
- Gribonval, Blanchard, Keriven, Traonmilin. **Compressive Statistical Learning with Random Feature Moments**. *Preprint* 2017. <arXiv:1706.07180>
- Keriven. **Sketching for Large-Scale Learning of Mixture Models**. *PhD Thesis*. <tel-01620815>
- Poon, Keriven, Peyré. **A Dual Certificates Analysis of Compressive Off-the-Grid Recovery**. *Submitted*
- **Code**: [sketchml.gforge.inria.fr](https://github.com/nkeriven/sketchml),
github: nkeriven

